Lecture 3 Nonparametric Methods

Statistical models with weak assumptions

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- Nonparametric regression
- Sparse additive models
- Constrained rank additive models
- Nonparametric graphical models

Nonparametric Regression

Given $(X_1, Y_1), \ldots, (X_n, Y_n)$ predict Y from X.

Assume only that $Y_i = m(X_i) + \epsilon_i$ where where m(x) is a smooth function of x.

The most popular methods are *kernel methods*. However, there are two types of kernels:

- Smoothing kernels
- Ø Mercer kernels

Smoothing kernels involve local averaging. Mercer kernels involve regularization.

Smoothing Kernels

Smoothing kernel estimator:

$$\widehat{m}_h(x) = \frac{\sum_{i=1}^n Y_i K_h(X_i, x)}{\sum_{i=1}^n K_h(X_i, x)}$$

where $K_h(x, z)$ is a *kernel* such as

$$\mathcal{K}_h(x,z) = \exp\left(-rac{\|x-z\|^2}{2h^2}
ight)$$

and h > 0 is called the *bandwidth*.

- $\hat{m}_h(x)$ is just a local average of the Y_i 's near x.
- The bandwidth *h* controls the bias-variance tradeoff: *Small h = large variance* while *large h = large bias*.

Example: Some Data – Plot of Y_i versus X_i



Example: $\widehat{m}(x)$



Х

$\widehat{m}(x)$ is a local average



Effect of the bandwidth h



small bandwidth



very small bandwidth



large bandwidth



medium bandwidth

Smoothing Kernels

$$\operatorname{Risk} = \mathbb{E}(Y - \widehat{m}_h(X))^2 = \operatorname{bias}^2 + \operatorname{variance} + \sigma^2.$$

bias² $\approx h^4$,

variance $\approx \frac{1}{nb^p}$ where p = dimension of X.

 $\sigma^2 = \mathbb{E}(Y - m(X))^2$ is the unavoidable prediction error.

small h: low bias, high variance (undersmoothing) *large h*: high bias, low variance (oversmoothing)

Risk Versus Bandwidth



h



optimal h

Estimating the Risk: Cross-Validation

To choose *h* we need to estimate the risk R(h). We can estimate the risk by using *cross-validation*.

- **①** Omit (X_i, Y_i) to get $\widehat{m}_{h,(i)}$, then predict: $\widehat{Y}_{(i)} = \widehat{m}_{h,(i)}(X_i)$.
- 2 Repeat this for all observations.
- 3 The cross-validation estimate of risk is:

$$\widehat{R}(h) = \frac{1}{n} \sum_{i=1}^{n} (Y_i - \widehat{Y}_{(i)})^2.$$

Shortcut formula:

$$\widehat{R}(h) = rac{1}{n} \sum_{i=1}^{n} \left(rac{Y_i - \widehat{Y}_i}{1 - L_{ii}}
ight)^2$$

where $L_{ii} = K_h(X_i, X_i) / \sum_t K_h(X_i, X_t)$.

- **1** Compute \hat{m}_h for each *h*.
- 2 Estimate the risk $\widehat{R}(h)$.
- 3 Choose bandwidth \hat{h} to minimize $\hat{R}(h)$.
- 4 Let $\widehat{m}(x) = \widehat{m}_{\widehat{h}}(x)$.

Example





Another Approach: Mercer Kernels

Instead of using local smoothing, we can optimize the fit to the data subject to regularization (penalization). Choose \hat{m} to minimize

$$\sum_{i} (Y_i - \widehat{m}(X_i))^2 + \lambda \text{ penalty(m)}$$

where penalty(m) is a *roughness penalty*.

 λ is a smoothing parameter that controls the amount of smoothing.

How do we construct a penalty that measures roughness? One approach is: *Mercer Kernels* and *RKHS = Reproducing Kernel Hilbert Spaces.*

A *Mercer Kernel* K(x, y) is symmetric and positive definite:

$$\int \int f(x)f(y)K(x,y)\,dx\,dy\geq 0\quad\text{for all }f.$$

Example: $K(x, y) = e^{-||x-y||^2/2}$.

Think of K(x, y) as the *similarity* between x and y. We will create a set of *basis functions* based on K.

Fix z and think of K(z, x) as a function of x. That is,

$$K(z,x)=K_z(x)$$

is a function of the second argument, with the first argument fixed.

Mercer Kernels

Let

$$\mathcal{F} = \left\{ f(\cdot) = \sum_{j=1}^{k} \beta_j \, K(z_j, \cdot) \right\}$$

Define a norm: $||f||_{\mathcal{K}} = \sum_{j} \sum_{k} \beta_{j} \beta_{k} \mathcal{K}(z_{j}, z_{k})$. $||f||_{\mathcal{K}}$ small means f smooth.

If
$$f = \sum_{r} \alpha_{r} K(z_{r}, \cdot)$$
, $g = \sum_{s} \beta_{s} K(w_{s}, \cdot)$, the inner product is
 $\langle f, g \rangle_{K} = \sum_{r} \sum_{s} \alpha_{r} \beta_{s} K(z_{r}, w_{s}).$

 \mathcal{F} is a reproducing kernel Hilbert space (RKHS) because

$$\langle f, K(x, \cdot) \rangle = f(x)$$

Nonparametric Regression: Mercer Kernels

Representer Theorem: Let \hat{m} minimize

$$J = \sum_{i=1}^{n} (Y_i - m(X_i))^2 + \lambda ||m||_{K}^2.$$

Then

$$\widehat{m}(x) = \sum_{i=1}^{n} \alpha_i \, K(X_i, x)$$

for some $\alpha_1, \ldots, \alpha_n$.

So, we only need to find the coefficients

$$\alpha = (\alpha_1, \ldots, \alpha_n).$$

Nonparametric Regression: Mercer Kernels

Plug $\widehat{m}(x) = \sum_{i=1}^{n} \alpha_i K(X_i, x)$ into *J*: $J = ||Y - \mathbb{K}\alpha||^2 + \lambda \alpha^T \mathbb{K}\alpha$

where $\mathbb{K}_{jk} = K(X_j, X_k)$

Now we find α to minimize *J*. We get: $\widehat{\alpha} = (\mathbb{K} + \lambda I)^{-1} Y$ and $\widehat{m}(x) = \sum_{i} \widehat{\alpha}_{i} K(X_{i}, x)$.

The estimator depends on the amount of regularization λ . Again, there is a bias-variance tradeoff. We choose λ by cross-validation. This is like the bandwidth in smoothing kernel regression.

Smoothing kernels: the bandwidth *h* controls the amount of smoothing.

Mercer kernels: norm $||f||_{\mathcal{K}}$ controls the amount of smoothing.

In practice these two methods give answers that are very similar.

Mercer Kernels: Examples



very small lambda





medium lambda

large lambda

Multiple Regression

Both methods extend easily to the case where *X* has dimension p > 1. For example, just use

$$K(x, y) = e^{-\|x-y\|^2/2}$$

However, this is hard to interpret and is subject to the curse of dimensionality. This means that the *statistical performance* and the *computational complexity* degrade as dimension *p* increases.

An alternative is to use something less nonparametric such as additive model where we restrict $m(x_1, \ldots, x_p)$ to be of the form:

$$m(x_1,\ldots,x_p)=\beta_0+\sum_j m_j(x_j).$$

- Nonparametric regression
- Sparse additive models
- Nonparametric graphical models

Additive Models

Model: $m(x) = \beta_0 + \sum_{j=1}^{p} m_j(x_j)$.

We can take $\hat{\beta}_0 = \overline{Y}$ and we will ignore β_0 from now on.

We want to minimize

$$\sum_{i=1}^{n} \left(Y_i - (m_1(X_{i1}) + \dots + m_p(X_{ip})) \right)^2$$

subject to m_j smooth.

Additive Models

The backfitting algorithm:

- Set *m̂*_j = 0
- Iterate until convergence:
 - Iterate over j:

•
$$R_i = Y_i - \sum_{k \neq j} \widehat{m}_k(X_{ik})$$

• $\widehat{m}_j \longleftarrow \operatorname{smooth}(X_j, R)$

Here, smooth(X_j , R) is any one-dimensional nonparametric regression function.

R: glm

But what if *p* is large?

Sparse Additive Models

Ravikumar, Lafferty, Liu and Wasserman, JRSS B (2009)

Additive Model:
$$Y_i = \sum_{j=1}^{p} m_j(X_{ij}) + \varepsilon_i, \quad i = 1, \dots, n$$

High dimensional: $n \ll p$, with most $m_j = 0$.

Optimization:minimize $\mathbb{E}\left(Y - \sum_{j} m_{j}(X_{j})\right)^{2}$ subject to $\sum_{j=1}^{p} \sqrt{\mathbb{E}(m_{j}^{2})} \leq L_{n}$ $\mathbb{E}(m_{j}) = 0$

Related work by Bühlmann and van de Geer (2009), Koltchinskii and Yuan (2010), Raskutti, Wainwright and Yu (2011)

$$C = \left\{ m \in \mathbb{R}^4 : \sqrt{m_1(x_1)^2 + m_1(x_2)^2} + \sqrt{m_2(x_1)^2 + m_2(x_2)^2} \le L \right\}$$



Stationary Conditions

Lagrangian

$$\mathcal{L}(f,\lambda) = \frac{1}{2} \mathbb{E} \left(Y - \sum_{j=1}^{p} m_j(X_j) \right)^2 + \lambda \sum_{j=1}^{p} \sqrt{\mathbb{E}(m_j^2(X_j))}$$

Let $R_j = Y - \sum_{k \neq j} m_k(X_k)$ be *j*th residual. Stationary condition

$$m_j - \mathbb{E}(R_j | X_j) + \lambda v_j = 0$$
 a.e.

where $v_j \in \partial \sqrt{\mathbb{E}(m_j^2)}$ satisfies

$$egin{array}{rcl} m{v}_j &=& \displaystylerac{m_j}{\sqrt{\mathbb{E}(m_j^2)}} & ext{if } \mathbb{E}(m_j^2)
eq 0 \ \ \sqrt{\mathbb{E}m{v}_j^2} &\leq& 1 & ext{otherwise} \end{array}$$

Stationary Conditions

Rewriting,

$$egin{array}{rcl} m_j + \lambda v_j &=& \mathbb{E}(R_j \,|\, X_j) \equiv P_j \ \left(1 + rac{\lambda}{\sqrt{\mathbb{E}(m_j^2)}}
ight) m_j &=& P_j \ ext{if} \ \mathbb{E}(P_j^2) > \lambda \ m_j &=& 0 \ ext{otherwise} \end{array}$$

This implies

$$m_j = \left[1 - \frac{\lambda}{\sqrt{\mathbb{E}(P_j^2)}}\right]_+ P_j$$

SpAM Backfitting Algorithm

Input: Data (X_i , Y_i), regularization parameter λ . Iterate until convergence:

For each j = 1, ..., p: Compute residual: $R_j = Y - \sum_{k \neq j} \widehat{m}_k(X_k)$ Estimate projection $P_j = \mathbb{E}(R_j | X_j)$, smooth: $\widehat{P}_j = S_j R_j$ Estimate norm: $s_j = \sqrt{\mathbb{E}[P_j]^2}$ Soft-threshold: $\widehat{m}_j \leftarrow \left[1 - \frac{\lambda}{\widehat{s}_i}\right]_{\perp} \widehat{P}_j$

Output: Estimator $\widehat{m}(X_i) = \sum_j \widehat{m}_j(X_{ij})$.

Example: Boston Housing Data

Predict house value Y from 10 covariates.

We added 20 irrelevant (random) covariates to test the method.

Y = house value; n = 506, p = 30.

$$Y = \beta_0 + m_1(\text{crime}) + m_2(\text{tax}) + \dots + \dots + m_{30}(X_{30}) + \epsilon$$

Note that $m_{11} = \cdots = m_{30} = 0$.

We choose λ by minimizing the estimated risk.

SpAM yields 6 nonzero functions. It correctly reports that $\hat{m}_{11} = \cdots = \hat{m}_{30} = 0.$

L_2 norms of fitted functions versus $1/\lambda$



Estimated Risk Versus λ





Example Fits

11=478.29 20 20 m8₁₀ 10 -10 -10 0.0 0.2 0.4 0.6 X8 0.8 1.0 0:0 0.2 0.4 0.6 0.8 1.0

RKHS Version

Raskutti, Wainwright and Yu (2011)

Sample optimization

$$\begin{split} \min_{f} \frac{1}{n} \sum_{i=1}^{n} \left(y_{i} - \sum_{j=1}^{p} m_{j}(x_{ij}) \right)^{2} + \lambda \sum_{j} \|m_{j}\|_{\mathcal{H}_{j}} + \mu \sum_{j} \|m_{j}\|_{L_{2}(\mathbb{P}_{n})} \\ \end{split}$$

where $\|m_{j}\|_{L_{2}(\mathbb{P}_{n})} = \sqrt{\frac{1}{n} \sum_{i=1}^{n} m_{j}^{2}(x_{ij})}. \end{split}$

By Representer Theorem, with $m_j(\cdot) = K_j \alpha_j$,

$$\min_{f} \frac{1}{n} \sum_{i=1}^{n} \left(\mathbf{y}_{i} - \sum_{j=1}^{p} \mathbf{K}_{j} \alpha_{j} \right)^{2} + \lambda \sum_{j} \sqrt{\alpha_{j}^{T} \mathbf{K}_{j} \alpha_{j}} + \mu \sum_{j} \sqrt{\alpha_{j}^{T} \mathbf{K}_{j}^{2} \alpha_{j}}$$

Finite dimensional SOCP, but no scalable algorithms known.

- Under what conditions do the backfitting algorithms converge?
- What guarantees can be given on the solution to the infinite dimensional optimization?
- Is it possible to simultaneously adapt to unknown smoothness and sparsity?
Multivariate Regression

 $Y \in \mathbb{R}^q$ and $X \in \mathbb{R}^p$. Regression function $M(X) = \mathbb{E}(Y | X)$.

Linear model M(X) = BX where $B \in \mathbb{R}^{q \times p}$.

Reduced rank regression: $r = \operatorname{rank}(B) \leq C$.

Recent work has studied properties and high dimensional scaling of reduced rank regression where nuclear norm

$$\|B\|_* := \sum_{j=1}^{\min(\rho,q)} \sigma_j(B)$$

as convex surrogate for rank constraint (Yuan et al., 2007; Negahban and Wainwright, 2011)

Nonparametric Reduced Rank Regression

Foygel, Horrell, Drton and Lafferty (2012)

Nonparametric multivariate regression $M(X) = (m^1(X), \dots, m^q(X))^T$

Each component an additive model

$$m^k(X) = \sum_{j=1}^p m_j^k(X_j)$$

What is the nonparametric analogue of $||B||_*$ penalty?

Low Rank Functions

What does it mean for a set of functions $m^1(x), \ldots, m^q(x)$ to be low rank?

Let x_1, \ldots, x_n be a collection of points.

We require the $n \times q$ matrix $\mathbb{M}(x_{1:n}) = [m^k(x_i)]$ is low rank.

Stochastic setting: $\mathbb{M} = [m^k(X_i)]$. Natural penalty is

$$\|\mathbb{M}\|_* = \sum_{s=1}^q \sigma_s(\mathbb{M}) = \sum_{s=1}^q \sqrt{\lambda_s(\mathbb{M}^T\mathbb{M})}$$

Population version:

$$\left\| M \right\|_* := \left\| \sqrt{\operatorname{Cov}(M(X))} \right\|_* = \left\| \Sigma(M)^{1/2} \right\|_*$$

Constrained Rank Additive Models (CRAM)

Let $\Sigma_i = \text{Cov}(M_i)$. Two natural penalties:

$$\left\| \Sigma_{1}^{1/2} \right\|_{*} + \left\| \Sigma_{2}^{1/2} \right\|_{*} + \dots + \left\| \Sigma_{p}^{1/2} \right\|_{*}$$
$$\left\| (\Sigma_{1}^{1/2} \Sigma_{2}^{1/2} \cdots \Sigma_{p}^{1/2}) \right\|_{*}$$

Population risk functional (first penalty)

$$\frac{1}{2}\mathbb{E}\left\|\mathbf{Y}-\sum_{j}\mathbf{M}_{j}(\mathbf{X}_{j})\right\|_{2}^{2}+\lambda\sum_{j}\left\|\left\|\mathbf{M}_{j}\right\|\right\|_{*}$$

Stationary Conditions

Subdifferential is
$$\partial |||F|||_* = \left\{ \left(\sqrt{\mathbb{E}(FF^{\top})} \right)^{-1} F + H \right\}$$
 where $|||H|||_{sp} \leq 1, \ \mathbb{E}(FH^{\top}) = 0, \ \mathbb{E}(FF^{\top})H = 0$

Let $P(X) := \mathbb{E}(Y | X)$ and consider optimization

$$\frac{1}{2}\mathbb{E}\left\|Y-M(X)\right\|_{2}^{2}+\lambda\left\|M\right\|_{2}$$

Let $\mathbb{E}(PP^T) = U \operatorname{diag}(\tau) U^T$ be the SVD. Define $M = U \operatorname{diag}([1 - \lambda/\sqrt{\tau}]_+) U^T P$

Then M is a stationary point of the optimization, satisfying

 $E(Y | X) = M(X) + \lambda V(X) \text{ a.e., for some } V \in \partial |||M|||_*$

CRAM Backfitting Algorithm (Penalty 1)

Input: Data (X_i, Y_i) , regularization parameter λ . Iterate until convergence: For each $i = 1, \ldots, p$. Compute residual: $R_i = Y - \sum_{k \neq i} \hat{f}_k(X_k)$ Estimate projection $P_i = \mathbb{E}(R_i | X_i)$, smooth: $\hat{P}_i = S_i R_i$ Compute SVD: $\frac{1}{n}\widehat{P}_{i}\widehat{P}_{i}^{T} = U \operatorname{diag}(\tau) U^{T}$ Soft-threshold: $\widehat{M}_i = U \operatorname{diag}([1 - \lambda/\sqrt{\tau}]_{\perp}) U^T \widehat{P}_i$ **Output**: Estimator $\widehat{M}(X_i) = \sum_i \widehat{M}_i(X_{ij})$.

Example

Data of Smith et al. (1962), chemical measurements for 33 individual urine specimens.

q = 5 response variables: pigment creatinine, and the concentrations (in mg/ml) of phosphate, phosphorus, creatinine and choline.

p = 3 covariates: weight of subject, volume and specific gravity of specimen.

We use Penalty 2 with local linear smoothing.

We take $\lambda = 1$ and bandwidth h = .3.



Statistical Scaling for Prediction

Let ${\mathcal F}$ be class of matrices of functions that have a functional SVD

 $M(X) = UDV(X)^{\top}$

where $\mathbb{E}(V^{\top}V) = I$, and $V(X) = [v_{sj}(X_j)]$ with each v_{sj} in a second-order Sobolev space. Define

$$\mathcal{M}_n = \left\{ \boldsymbol{M} : \boldsymbol{M} \in \mathcal{F}, \|\boldsymbol{D}\|_* = o\left(\frac{n}{q + \log(pq)}\right)^{1/4} \right\}.$$

Let \widehat{M} minimize the empirical risk $\frac{1}{n} \sum_{i} ||Y_i - \sum_{j} M_j(X_{ij})||_2^2$ over the class \mathcal{M}_n . Then

$$R(\widehat{M}) - \inf_{M \in \mathcal{M}_n} R(M) \stackrel{P}{\longrightarrow} 0$$

Canonical correlation analysis (CCA, Hotelling, 1936) is classical method for finding correlations between components of two random vectors $X \in \mathbb{R}^{p}$ and $Y \in \mathbb{R}^{q}$.

Sparse versions have been proposed for high dimensional data (Witten & Tibshirani, 2009)

Sparse additive models can be extended to this setting.

Sparse Additive Functional CCA

Balasubramanian, Puniyani and Lafferty (2012)

Population version of optimization:

$$\begin{split} \max_{f\in\mathcal{F},\;g\in\mathcal{G}} \mathbb{E}\left(f(X)g(Y)\right) & \text{subject to} \\ \max_{j} \mathbb{E}(f_{j}^{2}) \leq 1, \quad \sum_{j=1}^{p} \sqrt{\mathbb{E}(f_{j}^{2})} \leq C_{f} \\ \max_{k} \mathbb{E}(g_{k}^{2}) \leq 1, \quad \sum_{k=1}^{q} \sqrt{\mathbb{E}(g_{k}^{2})} \leq C_{g} \end{split}$$

Estimated with analogues of SpAM backfitting, together with screening procedures. See ICML paper.

- Nonparametric regression
- Sparse additive models
- Nonparametric graphical models

Regression vs. Graphical Models

assumptions	regression	graphical models
parametric	lasso	graphical lasso
nonparametric	sparse additive model	nonparanormal

The Nonparanormal (Liu, Lafferty, Wasserman, 2009)

A random vector $X = (X_1, \dots, X_p)^T$ has a *nonparanormal* distribution $X \sim NPN(\mu, \Sigma, f)$

in case

$$Z \equiv f(X) \sim N(\mu, \Sigma)$$

where $f(X) = (f_1(X_1), ..., f_p(X_p)).$

Joint density

$$p_X(x) = \frac{1}{(2\pi)^{p/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} \left(f(x) - \mu\right)^T \Sigma^{-1} \left(f(x) - \mu\right)\right\} \prod_{j=1}^p |f_j'(x_j)|$$

Semiparametric Gaussian copula

Examples













The Nonparanormal

- Define $h_j(x) = \Phi^{-1}(F_j(x))$ where $F_j(x) = \mathbb{P}(X_j \le x)$.
- Let Λ be the covariance matrix of Z = h(X). Then

$$X_j \amalg X_k \mid X_{\text{rest}}$$

if and only if
$$\Lambda_{jk}^{-1} = 0$$
.

- Hence we need to:
 - **1** Estimate $\hat{h}_j(x) = \Phi^{-1}(\hat{F}_j(x))$.
 - 2 Estimate covariance matrix of $Z = \hat{h}(X)$ using the glasso.

Winsorizing the CDF

Truncation to estimate \widehat{F}_j for n > p:



- LLW (2009) show that the resulting procedure has the same theoretical properties as the glasso, even with dimension *p* increasing with *n*.
- The truncation of the empirical distribution is crucial for the theoretical results when *p* is large, although in practice it does not seem to matter too much.
- If the nonparanormal is used when the data are actually Normal, little efficiency is lost.

Gene-Gene Interactions for Arabidopsis thaliana



source: wikipedia.org

Dataset from Affymetrix microarrays, sample size n = 118, p = 40 genes (isoprenoid pathway).

Example Results



Transformations for 3 Genes



- These genes have highly non-Normal marginal distributions.
- The graphs are different at these genes.

S&P Data (2003–2008): Graphical Lasso



S&P Data: Nonparanormal



S&P Data: Nonparanormal vs. Glasso



The Nonparanormal SKEPTIC

Liu, Han, Yuan, Lafferty & Wasserman, 2012

Assuming $X \sim NPN(f, \Sigma^0)$, we have

$$\Sigma_{jk}^{0}=2\sin\left(rac{\pi}{6}
ho_{jk}
ight)$$

where ρ is Spearman's rho:

$$\rho_{jk} := \operatorname{Corr}\left(F_j(X_j), F_k(X_k)\right).$$

Empirical estimate:

$$\widehat{\rho}_{jk} = \frac{\sum_{i=1}^{n} (r_{j}^{i} - \bar{r}_{j})(r_{k}^{i} - \bar{r}_{k})}{\sqrt{\sum_{i=1}^{n} (r_{j}^{i} - \bar{r}_{j})^{2} \cdot \sum_{i=1}^{n} (r_{k}^{i} - \bar{r}_{k})^{2}}}.$$

Similar relation holds for Kendall's tau.

The Nonparanormal SKEPTIC

Using a Hoeffding inequality for U-statistics, we get

$$\max_{jk} \left| \widehat{\Sigma}_{jk}^{\rho} - \Sigma_{jk}^{\mathsf{0}} \right| \leq \frac{3\sqrt{2}\pi}{2} \sqrt{\frac{\log d + \log n}{n}},$$

with probability at least $1 - 1/n^2$.

Can thus estimate the covariance at the parametric rate

Punch line: For graph and covariance estimation, no loss in statistical or computational efficiency comes from using Nonparanormal rather than Normal graphical model.

Graph-Valued Regression

- $(X_1, Y_1), \ldots, (X_n, Y_n)$ where Y_i is high-dimensional
- We'll discuss one particular version: *graph-valued regression* (Chen, Lafferty, Liu, Wasserman, 2010)
- Let G(x) be the graph for Y based on p(y|x)
- This defines a partition $\mathcal{X}_1, \ldots, \mathcal{X}_k$ where G(x) is constant over each partition.
- Three methods to find *G*(*x*):
 - Parametric
 - Kernel graph-valued regression
 - GO-CART (Graph-Optimized CART)

Graph-Valued Regression



- Gene associations from phenotype (or vice versa)
- Voting patterns from covariates on bills
- Stock interactions given market conditions, news items

Method I: Parametric

- Assume that Z = (X, Y) is jointly multivariate Gaussian.
- $\Sigma = \begin{pmatrix} \Sigma_X & \Sigma_{XY} \\ \Sigma_{YX} & \Sigma_Y \end{pmatrix}$.
- Get $\widehat{\Sigma}_X$, $\widehat{\Sigma}_Y$, and $\widehat{\Sigma}_{XY}$
- Get Ω_X by the glasso.

•
$$\widehat{\Sigma}_{Y|X} = \widehat{\Sigma}_Y - \widehat{\Sigma}_{YX}\widehat{\Omega}_X\widehat{\Sigma}_{XY}.$$

• But, the estimated graph does not vary with different values of X.

Method II: Kernel Smoothing

•
$$Y|X = x \sim N(\mu(x), \Sigma(x)).$$

$$\widehat{\Sigma}(x) = \frac{\sum_{i=1}^{n} K\left(\frac{\|x-x_i\|}{h}\right) (y_i - \widehat{\mu}(x)) (y_i - \widehat{\mu}(x))^T}{\sum_{i=1}^{n} K\left(\frac{\|x-x_i\|}{h}\right)}$$
$$\widehat{\mu}(x) = \frac{\sum_{i=1}^{n} K\left(\frac{\|x-x_i\|}{h}\right) y_i}{\sum_{i=1}^{n} K\left(\frac{\|x-x_i\|}{h}\right)}.$$

- Apply glasso to Σ
 ^ˆ
 ^ˆ
 (x)
- Easy to do but recovering X₁,..., X_k requires difficult post-processing.

- Run CART but use Gaussian log-likelihood (on held out data) to determine the splits
- This yields a partition $\mathcal{X}_1, \ldots, \mathcal{X}_k$ (and a corresponding tree)
- Run the glasso within each partition element

Simulated Data



Climate Data



- Nonparanormal: Unrestricted graphs, semiparametric
- We'll now trade off structural flexibility for greater nonparametricity

A distribution is supported by a forest F with edge set E(F) if

$$p(x) = \prod_{(i,j)\in E(F)} \frac{p(x_i, x_j)}{p(x_i) p(x_j)} \prod_{k\in V} p(x_k)$$

- For known marginal densities p(x_i, x_j), best tree obtained by minimum weight spanning tree algorithms.
- In high dimensions, a spanning tree will overfit.
- We prune back to a forest.

Step 1: Constructing a Full Tree

Compute kernel density estimates

$$\widehat{f}_{n_1}(x_i, x_j) = \frac{1}{n_1} \sum_{s \in \mathcal{D}_1} \frac{1}{h_2^2} \, \mathcal{K}\left(\frac{X_i^{(s)} - x_i}{h_2}\right) \, \mathcal{K}\left(\frac{X_j^{(s)} - x_j}{h_2}\right)$$

Estimate mutual informations

$$\widehat{I}_{n_1}(X_i, X_j) = \frac{1}{m^2} \sum_{k=1}^m \sum_{\ell=1}^m \widehat{f}_{n_1}(x_{ki}, x_{\ell j}) \log \frac{\widehat{f}_{n_1}(x_{ki}, x_{\ell j})}{\widehat{f}_{n_1}(x_{ki}) \, \widehat{f}_{n_1}(x_{\ell j})}$$

Run Kruskal's algorithm (Chow-Liu) on edge weights
Step 2: Pruning the Tree

Heldout risk

$$\widehat{R}_{n_2}(f_F) = -\sum_{(i,j)\in E} \int \widehat{f}_{n_2}(x_i, x_j) \log \frac{f(x_i, x_j)}{f(x_i) f(x_j)} dx_i dx_j$$

• Selected forest given by

$$\widehat{k} = \operatorname*{arg\,min}_{k \in \{0, \dots, p-1\}} \widehat{R}_{n_2} \left(\widehat{f}_{\widehat{T}_{n_1}^{(k)}} \right)$$

where $\widehat{T}_{n_1}^{(k)}$ is forest obtained after k steps of Kruskal

S&P Data: Forest Graph—Oops!



S&P Data: Forest Graph



S&P Data: Forest vs. Nonparanormal



Summary

- Smoothing kernels, Mercer kernels
- Sparse additive models
- Constrained rank additive models
- Nonparametric graphical models: Nonparanormal and forest-structured densities
- A little nonparametricity goes a long way.

Summary

- Thresholded backfitting algorithms derived from subdifferential calculus
- RKHS formulations are problematic
- Theory for infinite dimensional optimizations still incomplete
- Many extensions possible: Nonparanormal component analysis, etc.
- Variations on additive models enjoy most of the good statistical and computational properties of sparse linear models, with relaxed assumptions
- We're building a toolbox for large scale, high dimensional nonparametric inference.