## Continuous dependence of stationary distributions on parameters for stochastic predator-prey models

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| Abstract: |  |

# Continuous dependence of stationary distributions on parameters for stochastic predator-prey models 

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#### Abstract

This work studies the continuous dependence of the stationary distributions on the parameters for a stochastic predator-prey model with Beddington-DeAngelis functional response. We show that if the model is extinct (resp. permanent) for a parameter, it is still extinct (resp. permanent) in a neighbourhood of this parameter. In case of extinction, the Lyapunov exponent of predator quantity is negative and the prey quantity converges almost sure to the saturated situation where the predator is absent at an exponential rate. Under the condition permanence, the unique stationary distribution converges weakly to the degenerate measure concentrated at the unique limit cycle or at the globally asymptotical equilibrium when the diffusion term tends to 0 .


Keywords. Extinction; permanence; stationary distribution; limit cycle.
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## 1 Introduction

In ecology, a functional response is the intake rate of a consumer as a function of food density. It is associated with the numerical response, which is the reproduction rate of a consumer as a function of food density. Holling initiated the study of functional response in [8], where author introduced several types of such responses. The so-called Holling type II functional response is characterized by a decelerating intake rate following from the assumption that the consumer is limited by its capacity to process food. Similar to Holling-type functional response with an extra term describing mutual interference by predators, Beddington [2] and DeAngelis et al. [3] introduced the nowadays well-known Beddington-DeAngelis functional

[^0]response; see also [19] and references therein. Such a model represents most of the qualitative features of the ratio-dependent models but avoids the "low densities problem."

As the building blocks of the bio - and ecosystems, the basic premise of the predator-prey models is that species compete, evolve, and disperse for the purpose of seeking resources to sustain their struggle and existence. Let $\alpha=(r, K, m, a, b, c, \beta, \gamma)$ be the vector of parameters whose components are appropriate positive constants. Then a deterministic predator-prey model with Beddington-DeAngelis functional response of the form

$$
\left\{\begin{array}{l}
d x_{\alpha}(t)=\left(r x_{\alpha}(t)\left(1-\frac{x_{\alpha}(t)}{K}\right)-\frac{m x_{\alpha}(t) y_{\alpha}(t)}{a+b y_{\alpha}(t)+c x_{\alpha}(t)}\right) d t  \tag{1.1}\\
d y_{\alpha}(t)=y_{\alpha}(t)\left(-\gamma+\frac{\beta m x_{\alpha}(t)}{a+b y_{\alpha}(t)+c x_{\alpha}(t)}\right) d t,
\end{array}\right.
$$

where $x_{\alpha}(t)$ is the sizes of prey and $y_{\alpha}(t)$ is the size of predator at time $t$.
It is well-know that that the quadrants of the plan $\mathbb{R}_{+}^{2}=\{(x, y): x \geq 0, y \geq 0\}$ and its interior $\mathbb{R}_{+}^{2, o}=\{(x, y): x>0, y>0\}$ are invariant with respect to (1.1). Denote by $\Phi_{\alpha}^{\phi}(t)=\left(x_{\alpha}(t), y_{\alpha}(t)\right)$ the unique solution of (1.1) with initial value $\phi=(x, y) \in \mathbb{R}_{+}^{2}$. Let

$$
f(\phi, \alpha)=\left(r x\left(1-\frac{x}{K}\right)-\frac{m x y}{a+b y+c x} ;-\gamma y+\frac{\beta m x y}{a+b y+c x}\right)^{\top} .
$$

Consider the Lyapunov function $V(\phi, \alpha)=\beta x+y$. It is seen that

$$
\dot{V}(\phi, \alpha)=V_{\phi}(\phi, \alpha) f(\phi, \alpha)=\beta r x\left(1-\frac{x}{K}\right)-\gamma y \leq \frac{\beta(r+\gamma)^{2} K}{4 r}-\gamma V(\phi, \alpha),
$$

From this inequality, it is easy to prove that the set

$$
\mathcal{R}(\alpha):=\left\{(x, y) \in \mathbb{R}_{+}^{2}: x+\beta y \leq \frac{\beta(r+\gamma)^{2} K}{4 r \gamma}\right\}
$$

is also attractive set with respect to (1.1).
For any vector parameter $\alpha=(r, m, \beta, \gamma, a, b, c) \in \mathbb{R}_{+}^{7}$, construct the threshold value

$$
\begin{equation*}
\lambda_{\alpha}=-\gamma+\frac{\beta m K}{a+K c} \tag{1.2}
\end{equation*}
$$

When $\lambda_{\alpha}>0$, the system (1.1) has three nonnegative equilibriums $(0,0),(K, 0)$ and $\left(x_{\alpha}^{*}, y_{\alpha}^{*}\right)$. The long term behavior of the model (1.1) has been classified (see [15, 20] for example) by using the threshold value $\lambda_{\alpha}$ as follows.
lem1.1 Lemma 1.1 (see [20]). Let $\lambda_{\alpha}$ be a threshold value that is defined by (1.2). Then,

1. If $\lambda_{\alpha} \leq 0$ then the boundary equilibrium point $(K, 0)$ is globally asymptotically stable.
2. If $\lambda_{\alpha}>0$ and $b \geq \min \left\{\frac{c}{\beta}, \frac{m^{2} \beta^{2}-c^{2} \gamma^{2}}{\gamma \beta(m \beta-c \gamma)+m r \beta^{2}}\right\}$ then the positive equilibrium point $\phi_{\alpha}^{*}=$ $\left(x_{\alpha}^{*}, y_{\alpha}^{*}\right)$ of the system (1.1) is globally asymptotically stable.
3. If $\lambda_{\alpha}>0$ and $b<\min \left\{\frac{c}{\beta}, \frac{m^{2} \beta^{2}-c^{2} \gamma^{2}}{\gamma \beta(m \beta-c \gamma)+m r \beta^{2}}\right\}$ then the positive equilibrium point $\phi_{\alpha}^{*}=$ $\left(x_{\alpha}^{*}, y_{\alpha}^{*}\right)$ is unstable, and there is an exactly stable limit cycle $\Gamma_{\alpha}$.

Further, by the clarity of the positive equilibrium point formula and [7, Theorem 1.2, pp. 356], we have the following lemma.
lem1.2 Lemma 1.2. Let $\alpha=(r, m, \beta, \gamma, a, b, c)$ be the parameters of (1.1) such that $\lambda_{\alpha}>0$. Then,
(i) On the set $b \geq \min \left\{\frac{c}{\beta}, \frac{m^{2} \beta^{2}-c^{2} \gamma^{2}}{\gamma \beta(m \beta-c \gamma)+m r \beta^{2}}\right\}$, the mapping $\alpha \rightarrow\left(x_{\alpha}^{*}, y_{\alpha}^{*}\right)$ is continuous.
(ii) On $b<\min \left\{\frac{c}{\beta}, \frac{m^{2} \beta^{2}-c^{2} \gamma^{2}}{\gamma \beta(m \beta-c \gamma)+m r \beta^{2}}\right\}$ the mapping $\alpha \rightarrow \Gamma_{\alpha}$ is continuous in Hausdorff distance.

Let $\mathcal{K} \subset \mathbb{R}_{+}^{8}$ be a compact set. Denote $\mathcal{R}(\mathcal{K})=\cup_{\alpha \in \mathcal{K}} \mathcal{R}(\alpha)$. It is clear that $\overline{\mathcal{R}(\mathcal{K})}$ is a compact set. Since $f$ has continuous partial derivatives $\nabla_{\phi} f$ and $\nabla_{\alpha} f$, these derivatives are uniformly bounded on $\overline{\mathcal{R}}(\mathcal{K}) \times \mathcal{K}$. As a consequence, there exists a positive constants $L_{1}$ such that

$$
\begin{equation*}
\left\|f\left(\phi_{1}, \alpha_{1}\right)-f\left(\phi_{2}, \alpha_{2}\right)\right\| \leq L_{1}\left(\left\|\phi_{1}-\phi_{2} \mid+\right\| \alpha_{1}-\alpha_{2} \|\right), \quad \phi_{1}, \phi_{2} \in \mathcal{R}(\mathcal{K}) ; \alpha_{1}, \alpha_{2} \in \mathcal{K} . \tag{1.3}
\end{equation*}
$$

Let $T>0$. From the inequality (1.3), for any $\phi \in \mathcal{R}(\mathcal{K}) ; \alpha_{1}, \alpha_{2} \in \mathcal{K}$, we have

$$
\begin{aligned}
\sup _{0 \leq t \leq T}\left\|\Phi_{\alpha_{1}}^{\phi}(t)-\Phi_{\alpha_{2}}^{\phi}(t)\right\| & =\sup _{0 \leq t \leq T}\left\|\int_{0}^{t}\left[f\left(\Phi_{\alpha_{1}}^{\phi}(s), \alpha_{1}\right)-f\left(\Phi_{\alpha_{2}}^{\phi}(s), \alpha_{2}\right)\right] d s\right\| \\
& \leq \int_{0}^{T}\left\|f\left(\Phi_{\alpha_{1}}^{\phi}(s), \alpha_{1}\right)-f\left(\Phi_{\alpha_{2}}^{\phi}(s), \alpha_{2}\right)\right\| d s \\
& \leq L_{1} T\left\|\alpha_{1}-\alpha_{2}\right\|+L_{1} \int_{0}^{T} \sup _{0 \leq s \leq t}\left\|\Phi_{\alpha_{1}}^{\phi}(s)-\Phi_{\alpha_{2}}^{\phi}(s)\right\| d t
\end{aligned}
$$

Applying the Gronwall inequality we obtain

$$
\begin{equation*}
\sup _{0 \leq t \leq T}\left\|\Phi_{\alpha_{1}}^{\phi}(t)-\Phi_{\alpha_{2}}^{\phi}(t)\right\| \leq L_{1} T\left\|\alpha_{1}-\alpha_{2}\right\| e^{L_{1} T}, \quad \forall \phi \in \mathcal{R}(\mathcal{K}), \alpha_{1}, \alpha_{2} \in \mathcal{K} \tag{1.4}
\end{equation*}
$$

We now deal with the evolution of prey-predator model (1.1) in random environment, that is some parameters are perturbed by noises (see: $[6,10,11,14,17,18]$ ). Currently, one of the
important ways to model the influence of the environmental fluctuations in biological systems is to assume that the white noises affect the growth rates. Thus, in random environment, the parameters $r, \gamma$ become $r+\sigma_{1} \dot{B}_{1}$ and $\gamma \hookrightarrow \gamma-\sigma_{2} \dot{B}_{2}$, where $B_{1}$ and $B_{2}$ are two independent Brownian motions. Therefore, the equation (1.1) subjected to the environmental white noise can be rewritten

$$
\left\{\begin{array}{l}
d x_{\alpha, \sigma}(t)=\left(r x_{\alpha, \sigma}(t)\left(1-\frac{x_{\alpha, \sigma}(t)}{K}\right)-\frac{m x_{\alpha, \sigma}(t) y_{\alpha, \sigma}(t)}{a+b y_{\alpha, \sigma}(t)+c x_{\alpha, \sigma}(t)}\right) d t+\sigma_{1} x_{\alpha, \sigma}(t) d B_{1}(t),  \tag{1.5}\\
d y_{\alpha, \sigma}(t)=y_{\alpha, \sigma}(t)\left(-\gamma+\frac{\beta m x_{\alpha, \sigma}(t)}{a+b y_{\alpha, \sigma}(t)+c x_{\alpha, \sigma}(t)}\right) d t+\sigma_{2} y_{\alpha, \sigma}(t) d B_{2}(t),
\end{array}\right.
$$

where $\sigma=\left(\sigma_{1}, \sigma_{2}\right)$. Zou et al. in [20] has considered the existence of stationary distribution and the stochastic bifurcation for (1.5). They have proved that there is a critical point $b^{*}\left(\sigma_{1} ; \sigma_{2}\right)$ which depends on $\sigma_{1}$ and $\sigma_{2}$ such that system (1.5) undergoes a stochastic Hopf bifurcation at $b^{*}\left(\sigma_{1} ; \sigma_{2}\right)$. That is the shape of stationary distribution for system (1.5) changes from crater-like to peak-like. However, the conditions imposed on parameters are rather strict and some results in this paper need to be carefully discussed. In [6], Du et al. has constructed a threshold between the distinction and permanence (also the threshold of the existence of stationary distribution) to the system (1.5).

The main aim of this paper is to consider the robust of permanence and the continuous dependence of stationary distribution of the equation (1.5) on the data in case it exists. Precisely, we prove that if the model is extinct (resp. permanent) for a parameter, it is still extinct (resp. permanent) in a neighbourhood of this parameter. In case of extinction, the Lyapunov exponent of predator quantity is negative and the prey quantity converges almost sure to the saturated situation where the predator is absent. Further, if $\lambda_{\alpha_{0}}>0$ and $\alpha \rightarrow \alpha_{0}$ and $\sigma \rightarrow 0$, the stationary distribution $\mu_{\alpha, \sigma}$ of the equation (1.5) will converge weakly to the degenerate distribution concentrated on $\left(x_{\alpha_{0}}^{*}, y_{\alpha_{0}}^{*}\right)$ or on the limit cycle $\Gamma_{\alpha_{0}}$ of the system (1.1).

The paper is organized as follows. Next section deals with the main results. In section 3 , we give an example to illustrate that when $(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)$, the stationary distribution $\mu_{\alpha, \sigma}$ weakly converges to the degenerate distribution concentrated on $\left(x_{\alpha_{0}}^{*}, y_{\alpha_{0}}^{*}\right)$.

## 2 Main result

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space and let $B_{1}(t)$ and $B_{2}(t)$ be two mutually independent Brownian motions. It is well known that both $R_{+}^{2}$ and $R_{+}^{2, \mathrm{o}}$ (the interior of $\mathbb{R}_{+}^{2}$ )
are invariant to (1.5), i.e., for any initial value $\phi=(x(0), y(0)) \in \mathbb{R}_{+}^{2}$ (resp. in $\mathbb{R}_{+}^{2, \circ}$ ), there exists a unique global solution to (1.5) that remains in $\mathbb{R}_{+}^{2}$ (resp. $\in \mathbb{R}_{+}^{2,0}$ ) almost surely (see: [20]). Denote by $\Phi_{\alpha, \sigma}^{\phi}(t)=\left(x_{\alpha, \sigma}(t), y_{\alpha, \sigma}(t)\right)$ the unique solution of (1.5) with initial value $\phi \in \mathbb{R}_{+}^{2}$. For $d>0$ and $\delta>0$, let

$$
\begin{aligned}
\mathcal{U}_{\delta}(\alpha) & =\left\{\alpha^{\prime}=\left(r^{\prime}, m^{\prime}, \beta^{\prime}, \gamma^{\prime}, a^{\prime}, b^{\prime}, c^{\prime}\right) \in \mathbb{R}_{+}^{7}:\left\|\alpha^{\prime}-\alpha\right\| \leq \delta\right\}, \\
\mathcal{V}_{\delta}\left(\phi_{0}\right) & =\left\{\phi \in \mathbb{R}_{+}^{2}:\left\|\phi-\phi_{0}\right\| \leq \delta\right\} .
\end{aligned}
$$

the ball with the radius $\delta>0$ and center $\alpha$. Denote

$$
\mathcal{R}_{\delta}\left(\alpha_{0}\right)=\bigcup_{\alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right)} \mathcal{R}(\alpha)
$$

For any $R>0$, denote

$$
\mathbf{B}_{R}=\left\{\phi=(x, y) \in \mathbb{R}_{+}^{2}:\|\phi\| \leq R\right\} .
$$

Let $C^{2}\left(\mathbb{R}^{2}, \mathbb{R}_{+}\right)$be the family of all non-negative functions $V(\phi)$ on $\mathbb{R}^{2}$ which are twice continuously differentiable in $\phi$. For $V \in C^{2}\left(\mathbb{R}^{2}, \mathbb{R}_{+}\right)$, define the differential operator $\mathcal{L} V$ associated to the equation (1.5) is given by

$$
\begin{equation*}
\mathcal{L} V(\phi)=V_{\phi}(\phi) f(\phi, \alpha)+\frac{1}{2} \operatorname{trace}\left[\mathrm{~g}^{\top}(\phi, \sigma) \mathrm{V}_{\phi \phi}(\phi) \mathrm{g}(\phi, \sigma)\right] \tag{2.1}
\end{equation*}
$$

where $V_{\phi}(\phi)$ and $V_{\phi \phi}(\phi)$ are the gradient and Hessian of $V(\cdot), g$ is the diffusion coefficient of (1.5) given by

$$
g(\phi, \sigma)=\left(\begin{array}{cc}
\sigma_{1} x & 0 \\
0 & \sigma_{2} y
\end{array}\right) .
$$

By virtue of the symmetry of Brownian motions, in the following we are interested only $\sigma_{1} \geq 0, \sigma_{2} \geq 0$.
lem2.1 Lemma 2.1. Let $\mathcal{K} \in \mathbb{R}_{+}^{7, \mathrm{o}}$ be a compact set and $\bar{\sigma}>0$. Then for any $0 \leq p \leq \frac{2 \gamma_{*}}{\bar{\sigma}^{2}}$ we have

$$
\begin{equation*}
\mathbb{E}\left(V\left(\Phi_{\alpha, \sigma}^{\phi}(t)\right)\right) \leq e^{-H_{1} t} V(\phi)+\frac{H_{2}}{H_{1}}, \forall \alpha \in \mathcal{K},\|\sigma\| \leq \bar{\sigma}, t \geq 0 \tag{2.2}
\end{equation*}
$$

e2.2b
where $H_{1}=\frac{(1+p)}{2}\left(\gamma_{*}-\frac{p \bar{\sigma}^{2}}{2}\right), H_{2}=\sup _{\alpha \in \mathcal{K},|\sigma| \leq \bar{\sigma}} \sup _{\phi \in \mathbb{R}_{+}^{2}}\left\{\mathcal{L} V(\phi)+H_{1} V(\phi)\right\}$ and $\gamma_{*}=\inf \{\gamma$ : $(r, m, \beta, \gamma, a, b, c) \in \mathcal{K}\}$ and $V(\phi)=(\beta x+y)^{1+p}$.

As a consequence,

$$
\begin{equation*}
\sup \left\{\mathbb{E}\left\|\Phi_{\alpha, \sigma}^{\phi}(t)\right\|^{1+p}: \alpha \in \mathcal{K},\|\sigma\| \leq \bar{\sigma}, t \geq 0\right\}<\infty \tag{2.3}
\end{equation*}
$$

Proof. The differential operator $\mathcal{L} V(\phi)$ associated to the equation (1.5) is given by

$$
\begin{aligned}
\mathcal{L} V(\phi) & =(1+p)(\beta x+y)^{p}\left(\beta r x\left(1-\frac{x}{K}\right)-\gamma y\right)+\frac{p(1+p)}{2}(\beta x+y)^{p-1}\left(\beta^{2} \sigma_{1}^{2} x^{2}+\sigma_{2}^{2} y^{2}\right) \\
& \leq(1+p)\left(-\gamma+\frac{p\|\sigma\|^{2}}{2}\right)(\beta x+y)^{1+p}+\beta r(1+p)(\beta x+y)^{p} x\left(\frac{\gamma+r}{r}-\frac{x}{K}\right) \\
& \leq(1+p)\left(-\gamma_{*}+\frac{p \bar{\sigma}^{2}}{2}\right)(\beta x+y)^{1+p}+\beta r(1+p)(\beta x+y)^{p} x\left(\frac{\gamma+r}{r}-\frac{x}{K}\right) \\
& \leq H_{2}-H_{1} V(\phi) .
\end{aligned}
$$

where

$$
H_{1}=\frac{1+p}{2}\left(\gamma_{*}-\frac{p \bar{\sigma}^{2}}{2}\right)
$$

and

$$
H_{2}=\sup _{\alpha \in \mathcal{K},|\sigma| \leq \bar{\sigma}} \sup _{\phi \in \mathbb{R}_{+}^{2}}\left\{\mathcal{L} V(\phi)+H_{1} V(\phi)\right\}<\infty .
$$

Thus,

$$
\begin{equation*}
\mathcal{L} V(\phi) \leq H_{2}-H_{1} V(\phi) . \tag{2.4}
\end{equation*}
$$

By a standard argument as in [4, Lemma 2.3], from (2.4) it follows that

$$
\mathbb{E}\left(e^{H_{1} t} V\left(\Phi_{\alpha, \sigma}^{\phi}(t)\right)\right) \leq V(\phi)+\frac{H_{2}\left(e^{H_{1} t}-1\right)}{H_{1}}
$$

Thus,

$$
\mathbb{E}\left(V\left(\Phi_{\alpha, \sigma}^{\phi}(t)\right)\right) \leq e^{-H_{1} t} V(\phi)+\frac{H_{2}}{H_{1}},
$$

ie., we get (2.2).
By using the inequality $\|\phi\|^{1+p} \leq \max \left\{1, \gamma_{*}^{-(1+p)}\right\} V(\phi)$ and (2.2), we have

$$
\sup \left\{\mathbb{E}\left\|\Phi_{\alpha, \sigma}^{\phi}(t)\right\|^{1+p}: \alpha \in \mathcal{K},\|\sigma\| \leq \bar{\sigma}, t \geq 0\right\}<\infty
$$

Lemma is proved.
When the predator is absent, the evolution of prey follows the stochastic logistic equation on the boundary,

$$
\begin{equation*}
d \varphi_{\alpha, \sigma}(t)=r \varphi_{\alpha, \sigma}(t)\left(1-\frac{\varphi_{\alpha, \sigma}(t)}{K}\right) d t+\sigma_{1} \varphi_{\alpha, \sigma}(t) d B_{1}(t) \tag{2.5}
\end{equation*}
$$

Denote $\varphi_{\alpha, \sigma}(t)$ is a solution of the equation (2.5). By comparison theorem, it is seen that $x_{\alpha, \sigma}(t) \leq \varphi_{\alpha, \sigma}(t) \forall t \geq 0$ a.s., provided that $x_{\alpha, \sigma}(0)=\varphi_{\alpha, \sigma}(0)>0$ and $y_{\alpha, \sigma}(0) \geq 0$.
lem2.1 Lemma 2.2. Let $\left(x_{\alpha, \sigma}(t), y_{\alpha, \sigma}(t)\right)$ be a solution of the equation (1.5) and $\varphi_{\alpha, \sigma}(t)$ be a solution of Equation (2.5). Then,
(i) If $r<\frac{\sigma_{1}^{2}}{2}$ then the system is exponentially ruined in the sense that the Lyapunov exponents of $\varphi_{\alpha, \sigma}(\cdot), x_{\alpha, \sigma}(\cdot)$ and $y_{\alpha, \sigma}(\cdot)$ are negative.
(ii) In case $r-\frac{\sigma_{1}^{2}}{2}>0$, the equation (2.5) has a unique stationary distribution $\nu_{\alpha, \sigma}$ with the density

$$
p_{\alpha, \sigma}(x)=C x^{\frac{2 r}{\sigma_{1}^{2}}-2} e^{-\frac{2 r}{\sigma_{1}^{2} K} x}, x \geq 0
$$

Further $\nu_{\alpha, \sigma}$ weakly converges to $\delta_{K}(\cdot)$ as $\sigma_{1} \rightarrow 0$. Where $\delta_{K}(\cdot)$ is the Dirac measure with mass at $K$.

Proof. It is easy to verify that with the initial condition $\varphi_{\alpha, \sigma}(0)=x_{0}$, the equation (2.5) has a unique solution

$$
\begin{equation*}
\varphi_{\alpha, \sigma}(t)=\frac{x_{0} \exp \left\{\left(r-\frac{\sigma_{1}^{2}}{2}\right) t+\sigma B_{1}(t)\right\}}{K+r x_{0} \int_{0}^{t} \exp \left\{\left(r-\frac{\sigma_{1}^{2}}{2}\right) s+\sigma B_{1}(s)\right\} d s}, \tag{2.6}
\end{equation*}
$$

(see [16] for example).
Therefore, by the law of iterated logarithm we see that if $r-\frac{\sigma_{1}^{2}}{2}<0$ then

$$
\lim _{t \rightarrow \infty} \frac{\ln \varphi_{\alpha, \sigma}(t)}{t}=r-\frac{\sigma_{1}^{2}}{2}<0
$$

Using this estimate and the comparison theorem gets

$$
\limsup _{t \rightarrow \infty} \frac{\ln x_{\alpha, \sigma}(t)}{t} \leq \lim _{t \rightarrow \infty} \frac{\ln \varphi_{\alpha, \sigma}(t)}{t}=r-\frac{\sigma_{1}^{2}}{2}<0
$$

On other hand, it implied form the second equation in the system (1.5) that

$$
\begin{equation*}
\frac{\ln y_{\alpha, \sigma}(t)}{t}=\frac{\ln y_{\alpha, \sigma}(0)}{t}-\gamma-\frac{\sigma_{2}^{2}}{2}+\frac{1}{t} \int_{0}^{t} \frac{\beta m x_{\alpha, \sigma}(s)}{a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)} d s+\frac{\sigma_{2} B_{2}(t)}{t} . \tag{2.7}
\end{equation*}
$$

By using strong law of large numbers and (2.7), we have

$$
\limsup _{t \rightarrow \infty} \frac{\ln y_{\alpha, \sigma}(t)}{t}=-\gamma-\frac{\sigma_{2}^{2}}{2}<0
$$

The item (i) is proved.

We now prove the item (ii). Consider the Fokker-Planck equation with respect to (2.5),

$$
\begin{equation*}
\frac{\partial p_{\alpha, \sigma}(x, t)}{\partial t}=-\frac{\partial\left[r x\left(1-\frac{x}{K}\right) p_{\alpha, \sigma}(x, t)\right]}{\partial x}+\frac{\sigma_{1}^{2}}{2} \frac{\partial^{2}\left[x^{2} p_{\alpha, \sigma}(x)\right]}{\partial x^{2}} . \tag{2.8}
\end{equation*}
$$

It is easy to see that for $r-\frac{\sigma_{1}^{2}}{2}>0$ the equation (2.8) has a unique positive integrable solution

$$
p_{\alpha, \sigma}(x)=C x^{\frac{2 r}{\sigma_{1}^{2}}-2} e^{-\frac{2 r}{\sigma_{1}^{2} K} x}, x \geq 0
$$

which is a stationary density of (2.5). Where $C$ is the normalizing constant and defined by $C=\frac{1}{\Gamma\left(\frac{2 r}{\sigma_{1}^{2}}-1\right)}\left(\frac{2 r}{\sigma_{1}^{2} K}\right)^{\frac{2 r}{\sigma_{1}^{2}}-1}$ and $\Gamma(\cdot)$ is Gamma function. It means that the the equation (2.5) has a stationary distribution whose density is a Gamma distribution $\Gamma\left(\frac{2 r}{\sigma_{1}^{2}}-1, \frac{2 r}{\sigma_{1}^{2} K}\right)$. By direct calculation we have

$$
\lim _{\sigma \rightarrow 0} \mathbb{E}\left(\varphi_{\alpha, \sigma}(t)\right)=\lim _{\sigma_{1} \rightarrow 0}\left[K-\frac{K \sigma_{1}^{2}}{2 r}\right]=K
$$

and

$$
\lim _{\sigma_{1} \rightarrow 0} \operatorname{Var}\left(\varphi_{\alpha, \sigma}(\mathrm{t})\right)=\lim _{\sigma_{1} \rightarrow 0}\left[\frac{\mathrm{~K}^{2} \sigma_{1}^{4}}{4 \mathrm{r}^{2}}\left(\frac{2 \mathrm{r}}{\sigma_{1}^{2}}-1\right)\right]=0
$$

These equalities imply that the process $\varphi_{\alpha, \sigma}(t)$ converges to $K$ in $L_{2}$ as $\sigma_{1} \rightarrow 0$. The item (ii) of Lemma is proved.

By the item (i) of Lemma 2.2, from now on, we are interested only on the case $r>\frac{\sigma_{1}^{2}}{2}$. For any $\alpha \in \mathbb{R}_{+}^{7, \mathrm{o}}$ and $\sigma \geq 0$ we define a threshold

$$
\begin{equation*}
\lambda_{\alpha, \sigma}=-\gamma-\frac{\sigma_{2}^{2}}{2}+\int_{0}^{\infty} \frac{m \beta x}{a+c x} p_{\alpha, \sigma}(x) d x \tag{2.9}
\end{equation*}
$$

It is noted that when $\sigma=0$ we have $\lambda_{\alpha, 0}=\lambda_{\alpha}$ to be defined by (1.2).
lem2.0 Lemma 2.3. The mapping $(\alpha, \sigma) \rightarrow \lambda_{\alpha, \sigma}$ is continuous on the domain

$$
\mathcal{D}:=\left\{\alpha=(r, K, m, a, b, c, \beta, \gamma): \alpha \in \mathbb{R}_{+}^{8}, r>\frac{\sigma_{1}^{2}}{2}, \sigma_{1} \geq 0\right\}
$$

Proof. The integrality of the function $x^{\frac{2 r}{\sigma_{1}^{2}}-2} e^{-\frac{2 r}{\sigma_{1}^{2} K} x}, x \geq 0$ depends on two singular points 0 and $\infty$. For $\alpha_{0}=\left(r_{0}, K_{0}, m_{0}, a_{0}, b_{0}, c_{0}, \beta_{0}, \gamma_{0}\right) \in \mathcal{D}$ and $\sigma_{0}$ with $\sigma_{0,1}>0$, we can find a sufficiently small $\eta>0$ such that the function

$$
h(x)= \begin{cases}x^{\frac{2 r_{0}-\eta}{\sigma_{0,1}+\eta}-2} e^{-\frac{2 r_{0}-\eta}{\sigma_{0,1} K_{0}+\eta} x} & \text { for } 0<x<1 \\ x^{\frac{2 r_{0}+\eta}{\sigma_{0,1}^{2}-\eta}-2} e^{-\frac{2 r_{0}-\eta}{\sigma_{0,1}^{2} K+\eta} x} & \text { for } 1 \leq x\end{cases}
$$

is integrable on $\mathbb{R}_{+}$. Further, for all $\alpha$ to be closed to $\alpha_{0}$ and $\sigma$ to be closed to $\sigma_{0}$, we have $p_{\alpha, \sigma}(x) \leq h(x) \forall x \in \mathbb{R}_{+}$. Paying attention that the function $\frac{m \beta x}{a+c x}$ is bounded, we can use the Lebesgue dominated convergent theorem to get $\lim _{\alpha \rightarrow \alpha_{0}, \sigma \rightarrow \sigma_{0}} \lambda_{\alpha, \sigma_{0}}=\lambda_{\alpha, \sigma_{0}}$.

The case $\sigma_{0}=0$ follows from the item (ii) of Lemma 2.2.
Lemma is proved.
thm2.1 Theorem 2.4. If $\lambda_{\alpha, \sigma}<0$ then $y_{\alpha, \sigma}(t)$ has the Lyapunov exponent $\lambda_{\alpha, \sigma}$ and $x_{\alpha, \sigma}(t)-\varphi_{\alpha, \sigma}(t)$ converges almost surely to 0 as $t \rightarrow \infty$ at an exponential rate.

Proof. Since the function $h(u)=\frac{u}{A+u}$ is increasing in $u>0$, it follows from (2.7) and comparison theorem that

$$
\begin{aligned}
\frac{\ln y_{\alpha, \sigma}(t)}{t} & =\frac{\ln y_{\alpha, \sigma}(0)}{t}-\gamma-\frac{\sigma_{2}^{2}}{2}+\frac{1}{t} \int_{0}^{t} \frac{\beta m x_{\alpha, \sigma}(s)}{a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)} d s+\frac{\sigma_{2} B_{2}(t)}{t} \\
& \leq \frac{\ln y_{\alpha, \sigma}(0)}{t}-\gamma-\frac{\sigma_{2}^{2}}{2}+\frac{1}{t} \int_{0}^{t} \frac{\beta m \varphi_{\alpha, \sigma}(s)}{a+c \varphi_{\alpha, \sigma}(s)} d s+\frac{\sigma_{2} B_{2}(t)}{t}
\end{aligned}
$$

Letting $t \rightarrow \infty$ and applying the law of large number to the process $\varphi_{\alpha, \sigma}$ obtain

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} \frac{\ln y_{\alpha, \sigma}(t)}{t} \leq-\gamma-\frac{\sigma_{2}^{2}}{2}+\int_{0}^{\infty} \frac{\beta m x}{a+c x} p_{\alpha, \sigma}(x) d x=\lambda_{\alpha, \sigma} . \tag{2.10}
\end{equation*}
$$

We now prove that the process $x_{\alpha, \sigma}(t)-\varphi_{\alpha, \sigma}(t)$ converges almost surely to 0 by estimating the rate of convergence $\varphi_{\alpha, \sigma}(t)-x_{\alpha, \sigma}(t)$ when $t \rightarrow \infty$. Using the Itô's formula we get

$$
\begin{equation*}
\ln x_{\alpha, \sigma}(t)=\ln x_{0}+\int_{0}^{t}\left(r\left(1-\frac{x_{\alpha, \sigma}(s)}{K}\right)-\frac{m y_{\alpha, \sigma}(s)}{a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)}-\frac{\sigma_{1}^{2}}{2}\right) d s+\sigma_{1} B_{1}(t) \tag{2.11}
\end{equation*}
$$

and

$$
\begin{equation*}
\ln \varphi_{\alpha, \sigma}(t)=\ln \varphi_{\alpha, \sigma}(0)+\int_{0}^{t}\left(r\left(1-\frac{\varphi_{\alpha, \sigma}(s)}{K}\right)-\frac{\sigma_{1}^{2}}{2}\right) d s+\sigma_{1} B_{1}(t) \tag{2.12}
\end{equation*}
$$

From (2.11), (2.12) and inequalities $\frac{m y}{a+b y+c x} \leq \frac{m y}{a}, \forall x, y>0$ and $x_{\alpha, \sigma}(t) \leq \varphi_{\alpha, \sigma}(t), t \geq$ 0 , we have

$$
\begin{align*}
0 \leq \limsup _{t \rightarrow \infty} \frac{\ln \varphi_{\alpha, \sigma}(t)-\ln x_{\alpha, \sigma}(t)}{t} \leq \limsup _{t \rightarrow \infty} \frac{1}{t} \int_{0}^{t} & \left(\frac{r}{K}\left(x_{\alpha, \sigma}(s)-\varphi_{\alpha, \sigma}(s)\right)+\frac{m}{a} y_{\alpha, \sigma}(s)\right) d s \\
& \leq \frac{m}{a} \limsup _{t \rightarrow \infty} \frac{1}{t} \int_{0}^{t} y_{\alpha, \sigma}(s) d s=0 \tag{2.13}
\end{align*}
$$

From (2.6), it is easy to see that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{\ln \varphi_{\alpha, \sigma}(t)}{t}=0, \text { a.s. } \tag{2.14}
\end{equation*}
$$

Combining (2.14) and (2.13) we obtain

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{\ln x_{\alpha, \sigma}(t)}{t}=0, \text { a.s. } \tag{2.15}
\end{equation*}
$$

Hence, from (2.10)

$$
\begin{equation*}
\limsup _{t \rightarrow \infty} \frac{\ln y_{\alpha, \sigma}(t)-\ln x_{\alpha, \sigma}(t)}{t} \leq \lambda_{\alpha, \sigma}<0 . \tag{2.16}
\end{equation*}
$$

Otherwise,

$$
\begin{equation*}
d\left(\frac{1}{x_{\alpha, \sigma}(t)}\right)=\left(\frac{\sigma_{1}^{2}-r}{x_{\alpha, \sigma}(t)}+\frac{r}{K}+\frac{m y_{\alpha, \sigma}(t)}{x_{\alpha, \sigma}(t)\left(a+b y_{\alpha, \sigma}(t)+c x_{\alpha, \sigma}(t)\right)}\right) d t-\frac{\sigma_{1}}{x_{\alpha, \sigma}(t)} d B_{1}(t), \tag{2.17}
\end{equation*}
$$

```
ito_1/x
```

and

$$
\begin{equation*}
d\left(\frac{1}{\varphi_{\alpha, \sigma}(t)}\right)=\left(\frac{\sigma_{1}^{2}-r}{\varphi_{\alpha, \sigma}(t)}+\frac{r}{K}\right) d t-\frac{\sigma_{1}}{\varphi_{\alpha, \sigma}(t)} d B_{1}(t) . \tag{2.18}
\end{equation*}
$$

Put $z(t)=\frac{1}{x_{\alpha, \sigma}(t)}-\frac{1}{\varphi_{\alpha, \sigma}(t)}$. We see that $z(t) \geq 0$ for all $t \geq 0$ and

$$
d z(t)=\left(\left(\sigma_{1}^{2}-r\right) z(t)+\frac{m y_{\alpha, \sigma}(t)}{x_{\alpha, \sigma}(t)\left(a+b y_{\alpha, \sigma}(t)+c x_{\alpha, \sigma}(t)\right)}\right) d t-\sigma_{1} z(t) d B_{1}(t)
$$

In view of the variation of constants formula [13, Theorem 3.1, pp.96], it yields that

$$
\begin{equation*}
z(t)=c_{1} \Psi(t) \int_{0}^{t} \Psi^{-1}(s) \frac{m y_{\alpha, \sigma}(s)}{x_{\alpha, \sigma}(s)\left(a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)\right)} d s \tag{2.19}
\end{equation*}
$$

where

$$
\begin{equation*}
\Psi(t)=e^{\left(\frac{\sigma_{1}^{2}}{2}-r\right) t-\sigma_{1} B_{1}(t)} \tag{2.20}
\end{equation*}
$$

It is easy to see that

$$
\begin{equation*}
\lim _{t \rightarrow \infty} \frac{\ln \Psi(t)}{t}=\frac{\sigma_{1}^{2}}{2}-r . \tag{2.21}
\end{equation*}
$$

Let $0<\bar{\lambda}<\max \left\{\frac{r-\sigma_{1}^{2}}{2},-\lambda_{\alpha, \sigma}\right\}$ be arbitrary and let us choose $\varepsilon>0$ such that $0<\bar{\lambda}+3 \varepsilon<$ $\max \left\{r-\frac{\sigma_{1}^{2}}{2},-\lambda_{\alpha, \sigma}\right\}$. From (2.21), there are two positive random variables $\eta_{1}, \eta_{2}$ such that

$$
\begin{equation*}
\eta_{1} e^{\left(\frac{\sigma_{1}^{2}}{2}-r-\varepsilon\right) t} \leq \Psi(t) \leq \eta_{2} e^{\left(\frac{\sigma_{1}^{2}}{2}-r+\varepsilon\right) t}, \forall t \geq 0 \text { a.s. } \tag{2.22}
\end{equation*}
$$

Further, follows from (2.16), there exists a positive random variable $\eta_{3}$ satisfies

$$
\begin{equation*}
\frac{y_{\alpha, \sigma}(t)}{x_{\alpha, \sigma}(t)} \leq \eta_{3} e^{\left(\lambda_{\alpha, \sigma}+\varepsilon\right) t}, \forall t \geq 0 \text { a.s. } \tag{2.23}
\end{equation*}
$$

Combining (2.19), (2.22) and (2.23), gets

$$
e^{\bar{\lambda} t} z(t) \leq \frac{c_{1} m \eta_{2} \eta_{3}}{a \eta_{1}} e^{\left(\bar{\lambda}+\frac{\sigma_{1}^{2}}{2}-r+\varepsilon\right) t} \int_{0}^{t} e^{\left(r-\frac{\sigma_{1}^{2}}{2}+\lambda_{\alpha, \sigma}+2 \varepsilon\right) s} d s
$$

Thus,

$$
0 \leq \lim _{t \rightarrow \infty} e^{\bar{\lambda} t} z(t) \leq \frac{c_{1} m \eta_{2} \eta_{3}}{a \eta_{1}\left(r-\frac{\sigma_{1}^{2}}{2}+\lambda_{\alpha, \sigma}+2 \varepsilon\right)^{t \rightarrow \infty}} \lim _{t}\left(e^{\left(\lambda_{\alpha, \sigma}+\bar{\lambda}+3 \varepsilon\right) t}-e^{\left(\bar{\lambda}+\frac{\sigma_{1}^{2}}{2}-r+\varepsilon\right) t}\right)=0
$$

As a result

$$
\begin{equation*}
\lim _{t \rightarrow \infty} e^{\bar{\lambda} t} z(t)=\lim _{t \rightarrow \infty} e^{\bar{\lambda} t}\left(\frac{1}{x_{\alpha, \sigma}(t)}-\frac{1}{\varphi_{\alpha, \sigma}(t)}\right)=0 \tag{2.24}
\end{equation*}
$$

Since $\lim _{t \rightarrow \infty} \frac{\ln \varphi_{\alpha, \sigma}(t)}{t}=0, \lim _{t \rightarrow \infty} e^{-\frac{\bar{t} t}{2}} \varphi_{\alpha, \sigma}^{2}(t)=0$. Using (2.24) obtains

$$
\begin{aligned}
\lim _{t \rightarrow \infty} e^{\frac{\bar{\lambda} t}{2}}\left(\varphi_{\alpha, \sigma}(t)-x_{\alpha, \sigma}(t)\right) & =\lim _{t \rightarrow \infty} e^{\frac{\bar{\lambda} t}{2}} \varphi_{\alpha, \sigma}(t) x_{\alpha, \sigma}(t)\left(\frac{1}{x_{\alpha, \sigma}(t)}-\frac{1}{\varphi_{\alpha, \sigma}(t)}\right) \\
& =\lim _{t \rightarrow \infty} e^{-\frac{\lambda t}{2}} \varphi_{\alpha, \sigma}(t) x_{\alpha, \sigma}(t) e^{\bar{\lambda} t}\left(\frac{1}{x_{\alpha, \sigma}(t)}-\frac{1}{\varphi_{\alpha, \sigma}(t)}\right)=0
\end{aligned}
$$

It means, $x_{\alpha, \sigma}(t)-\varphi_{\alpha, \sigma}(t)$ converges almost surely to 0 as $t \rightarrow \infty$ at an exponential rate.
We now turn to the estimate of Lyapunov exponent of $y_{\alpha, \sigma}$. From (2.7) we get

$$
\begin{aligned}
\frac{\ln y_{\alpha, \sigma}(t)}{t} & =\frac{\ln y_{\alpha, \sigma}(0)}{t}-\gamma-\frac{\sigma_{2}^{2}}{2}+\frac{1}{t} \int_{0}^{t} \frac{\beta m x_{\alpha, \sigma}(s)}{a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)} d s+\frac{\sigma_{2} B_{2}(t)}{t} \\
& =\frac{\ln y_{\alpha, \sigma}(0)}{t}-\gamma-\frac{\sigma_{2}^{2}}{2}+\frac{1}{t} \int_{0}^{t} \frac{\beta m \varphi_{\alpha, \sigma}(s)}{a+c \varphi_{\alpha, \sigma}(s)} d s+\frac{\sigma_{2} B_{2}(t)}{t} \\
& +\frac{1}{t} \int_{0}^{t} \beta m\left(\frac{x_{\alpha, \sigma}(s)}{a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)}-\frac{\varphi_{\alpha, \sigma}(s)}{a+c \varphi_{\alpha, \sigma}(s)}\right) d s .
\end{aligned}
$$

Since $\lim _{t \rightarrow \infty}\left(x_{\alpha, \sigma}(t)-\varphi_{\alpha, \sigma}(t)\right)=0$ and $\lim _{t \rightarrow \infty} y_{\alpha, \sigma}(t)=0$, it is easy to see that

$$
\lim _{t \rightarrow \infty} \frac{1}{t} \int_{0}^{t} \beta m\left(\frac{x_{\alpha, \sigma}(s)}{a+b y_{\alpha, \sigma}(s)+c x_{\alpha, \sigma}(s)}-\frac{\varphi_{\alpha, \sigma}(s)}{a+c \varphi_{\alpha, \sigma}(s)}\right) d s=0
$$

Thus,

$$
\lim _{t \rightarrow \infty} \frac{\ln y_{\alpha, \sigma}(t)}{t}=\lim _{t \rightarrow \infty}\left(\frac{\ln y_{\alpha, \sigma}(0)}{t}-\gamma-\frac{\sigma_{2}^{2}}{2}+\frac{1}{t} \int_{0}^{t} \frac{\beta m \varphi_{\alpha, \sigma}(s)}{a+c \varphi_{\alpha, \sigma}(s)} d s+\frac{\sigma_{2} B_{2}(t)}{t}\right)=\lambda_{\alpha, \sigma} .
$$

The proof is complete.
The following lemma is similar to one in [5].
lem2.3 Lemma 2.5. For $T, \varsigma>0$ and $\alpha_{0} \in \mathbb{R}_{+}^{7,0}$, there exists a number $\kappa$ and $\delta$ such that for all $\alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right)$ and $0<\|\sigma\|<\kappa$,

$$
\begin{equation*}
\mathbb{P}\left\{\left\|\Phi_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha_{0}}^{\phi}(t)\right\| \geq \varsigma, \text { for some } t \in[0, T]\right\}<\exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}, \phi \in \mathcal{R}_{\delta}\left(\alpha_{0}\right) \tag{2.25}
\end{equation*}
$$

Proof. Let $0<\delta \leq \frac{\varsigma}{2 L_{1} T e^{L_{1} T}}$. From (1.4) we have

$$
\begin{equation*}
\sup _{0 \leq t \leq T}\left\|\Phi_{\alpha}^{\phi}(t)-\Phi_{\alpha_{0}}^{\phi}(t)\right\| \leq \frac{\varsigma}{2}, \quad \forall \alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right), \phi \in \mathcal{R}_{\delta}\left(\alpha_{0}\right) . \tag{2.26}
\end{equation*}
$$

Let $R>0$ be large enough such that $\mathcal{R}_{\delta}\left(\alpha_{0}\right) \subset \mathbf{B}_{R}$ and let $h_{R}(\cdot)$ be a twice differentiable function such that

$$
h_{R}(\phi)=\left\{\begin{array}{ll}
1 & \text { if }\|\phi\| \leq R \\
0 & \text { if }\|\phi\|>R+1
\end{array}, \quad 0 \leq h_{R} \leq 1\right.
$$

Put

$$
f_{h}(\phi, \alpha)=h(\phi) f(\phi, \alpha)=\binom{h(\phi) f^{(1)}(\phi, \alpha)}{h(\phi) f^{(2)}(\phi, \alpha)}
$$

and

$$
g_{h}(\phi)=h(x, y) g(x, y)=h(x, y)\left(\begin{array}{cc}
\sigma_{1} x & 0 \\
0 & \sigma_{2} y
\end{array}\right)
$$

It is seen that $f_{h}(\phi, \alpha)$ is a Lipschitz function, i.e., there exist $M>0$ such that

$$
\begin{equation*}
\left\|f_{h}\left(\phi_{1}, \alpha\right)-f_{h}\left(\phi_{2}, \alpha\right)\right\| \leq M\left\|\phi_{2}-\phi_{1}\right\|, \quad \forall \alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right), \phi_{1}, \phi_{2} \in \mathbb{R}_{+}^{2} \tag{2.27}
\end{equation*}
$$

If we choose $M \geq 2 R^{2}$ we also have

$$
\begin{equation*}
\left\|g_{h}(\phi) g_{h}^{\top}(\phi)\right\| \leq M\|\sigma\|^{2}, \quad \forall \phi \in \mathbb{R}_{+}^{2} \tag{2.28}
\end{equation*}
$$

Let $\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)$ be the solution starting at $\phi \in \mathcal{R}_{\delta}\left(\alpha_{0}\right)$ of the equation

$$
\begin{equation*}
d \widetilde{\Phi}(t)=f_{h}(\widetilde{\Phi}(t), \alpha) d t+g_{h}(\widetilde{\Phi}(t)) d B(t) \tag{2.29}
\end{equation*}
$$

where $B(t)=\left(B_{1}(t), B_{2}(t)\right)^{\top}$. Define the stopping time

$$
\begin{equation*}
\tau_{R}^{\phi}=\inf \left\{t \geq 0:\left\|\Phi_{\alpha, \sigma}^{\phi}(t)\right\| \geq R\right\} \tag{2.30}
\end{equation*}
$$

It is easy to see that $\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)=\Phi_{\alpha, \sigma}^{\phi}(t)$ up to time $\tau_{R}^{\phi}$. Since the state space $\mathcal{R}_{\delta}\left(\alpha_{0}\right)$ of (1.1) is contained in $\mathbf{B}_{R}$, the solution $\Phi_{\alpha}^{\phi}(\cdot)$ of (1.1) is also the solution of the equation

$$
d \Phi(t)=f_{h}(\Phi(t), \alpha) d t, t \geq 0
$$

with initial value $\phi \in \mathcal{R}_{\delta}\left(\alpha_{0}\right)$. For all $t \in[0, T]$, using Itô's formula we have

$$
\begin{align*}
\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha}^{\phi}(t)\right\|^{2}= & 2 \int_{0}^{t}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right)^{\top}\left(f_{h}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s), \alpha\right)-f_{h}\left(\Phi_{\alpha}^{\phi}(s), \alpha\right)\right) d s \\
& +\int_{0}^{t} h\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right) \operatorname{trace}\left(\mathrm{g}_{\mathrm{h}}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(\mathrm{s})\right) \mathrm{g}_{\mathrm{h}}^{\top}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(\mathrm{s})\right)\right) \mathrm{ds} \\
& +2 \int_{0}^{t}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right)^{\top} g_{h}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right) d B(t) . \tag{2.31}
\end{align*}
$$

By the exponential martingale inequality, for $T, \varsigma>0$, there exists a number $\kappa=\kappa(T, \varsigma)$ such that $\mathbb{P}(\widetilde{\Omega}) \geq 1-\exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}$, where

$$
\begin{aligned}
& \widetilde{\Omega}=\left\{\operatorname { s u p } _ { t \in [ 0 , T ] } \left[\int_{0}^{t}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right)^{\top} g_{h}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right) d B(t)\right.\right. \\
& \left.\left.-\frac{1}{2\|\sigma\|^{2}} \int_{0}^{t}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right)^{\top} g_{h}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right) g_{h}^{\top}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right)\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right) d s\right] \leq \kappa, \phi \in \mathcal{R}_{\delta}\left(\alpha_{0}\right)\right\} .
\end{aligned}
$$

From (2.27) and (2.28), it implies that for all $\omega \in \widetilde{\Omega}$,

$$
\begin{array}{r}
\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha}^{\phi}(t)\right\|^{2} \leq 2 \int_{0}^{t}\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right\|\left\|f_{h}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s), \alpha\right)-f_{h}\left(\Phi_{\alpha}^{\phi}(s), \alpha\right)\right\| d s \\
\quad+\int_{0}^{t} h\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right) \operatorname{trace}\left(\mathrm{g}_{\mathrm{h}}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(\mathrm{s})\right) \mathrm{g}_{\mathrm{h}}^{\top}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(\mathrm{s})\right)\right) \mathrm{ds} \\
+\frac{1}{\|\sigma\|^{2}} \int_{0}^{t}\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right\|^{2}\left\|g_{h}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right) g_{h}^{\top}\left(\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)\right)\right\| d s+2 \int_{0}^{t} \kappa d s \\
\leq 3 M \int_{0}^{t}\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(s)-\Phi_{\alpha}^{\phi}(s)\right\|^{2} d s+\left(M\|\sigma\|^{2}+2 \kappa\right) T \tag{2.32}
\end{array}
$$

For all $t \in[0, T]$, an application of Gronwall-Belmann's inequality implies that

$$
\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha}^{\phi}(t)\right\| \leq \sqrt{\left(M\|\sigma\|^{2}+2 \kappa\right) T \exp \{3 M T\}}
$$

in the set $\widetilde{\Omega}$. Choosing $\kappa$ is sufficiently small such that $\left(M \kappa^{2}+2 \kappa\right) T \exp \{3 M T\} \leq \frac{\varsigma^{2}}{4}$ implies

$$
\begin{equation*}
\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha}^{\phi}(t)\right\| \leq \frac{\varsigma}{2}, \text { for all } \alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right), 0<\|\sigma\|<\kappa, \omega \in \widetilde{\Omega} \tag{2.33}
\end{equation*}
$$

From (2.33), (2.26) and triangle inequality, we have

$$
\left\|\widetilde{\Phi}_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha_{0}}^{\phi}(t)\right\| \leq \varsigma \forall \alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right), t \in[0, T], \omega \in \widetilde{\Omega}
$$

It also follows from this inequality that when $\omega \in \widetilde{\Omega}$ we have $\tau_{R}>T$, which implies

$$
\mathbb{P}\left\{\left\|\Phi_{\alpha, \sigma}^{\phi}(t)-\Phi_{\alpha_{0}}^{\phi}(t)\right\|<\varsigma, \text { for all } t \in[0, T]\right\} \geq \mathbb{P}\left(\Omega_{1}\right) \geq 1-\exp \left\{\frac{\kappa}{\|\sigma\|^{2}}\right\}
$$

holds for all $0<\|\sigma\|<\kappa$ and $\alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right)$. The proof is complete.
thm2.4 Theorem 2.6. Let $\alpha_{0}=\left(r_{0}, m_{0}, \beta_{0}, \gamma_{0}, a_{0}, b_{0}, c_{0}\right)$ be a vector of parameters of the system (1.1) such that $\lambda_{\alpha_{0}}>0$ and $b_{0}<\min \left\{\frac{c_{0}}{\beta_{0}}, \frac{m_{0}^{2} \beta_{0}^{2}-c_{0}^{2} \gamma_{0}^{2}}{\gamma_{0} \beta_{0}\left(m_{0} \beta_{0}-c_{0} \gamma_{0}\right)+m_{0} r_{0} \beta_{0}^{2}}\right\}$. Then, there exist $\delta_{1}>0$ and $\bar{\sigma}>0$ such that for all $\alpha \in \mathcal{U}_{\delta_{1}}\left(\alpha_{0}\right)$ and $0<\|\sigma\| \leq \bar{\sigma}$, the Markov process $\Phi_{\alpha, \sigma}^{\phi}(t)=$
$\left(x_{\alpha, \sigma}(t), y_{\alpha, \sigma}(t)\right)$ has a unique stationary distribution $\mu_{\alpha, \sigma}$. Further, $\mu_{\alpha, \sigma}$ is concentrated on $\mathbb{R}_{+}^{2,0}$ and has the density with respect to Lebesgue measure. Besides, for any open set $\mathcal{V}$ containing $\Gamma_{\alpha_{0}}$ we have

$$
\begin{equation*}
\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(\mathcal{V})=1 \tag{2.34}
\end{equation*}
$$

where $\Gamma_{\alpha_{0}}$ is limit cycle of the system (1.1) corresponding to the parameter $\alpha_{0}$.
Proof. Since $\lambda_{\alpha_{0}}=-\gamma_{0}+\frac{K m_{0} \beta_{0}}{a_{0}+K c_{0}}>0$ and $b_{0}<\min \left\{\frac{c_{0}}{\beta_{0}}, \frac{m_{0}^{2} \beta_{0}^{2}-c_{0}^{2} \gamma_{0}^{2}}{\gamma_{0} \beta_{0}\left(m_{0} \beta_{0}-c_{0} \gamma_{0}\right)+m_{0} r_{0} \beta_{0}^{2}}\right\}$, we can use Lemma 2.3 to find $\delta_{1}>0$ and $\bar{\sigma}$ such that

$$
\begin{aligned}
\lambda_{\alpha, \sigma} & =-\gamma-\frac{\sigma_{2}^{2}}{2}+\int_{0}^{\infty} \frac{m \beta x}{a+c x} p_{\alpha, \sigma}(x) d x>0 \\
b & <\min \left\{\frac{c}{\beta}, \frac{m^{2} \beta^{2}-c^{2} \gamma^{2}}{\gamma \beta(m \beta-c \gamma)+m r \beta^{2}}\right\}
\end{aligned}
$$

hold for all $\alpha \in \mathcal{U}_{\delta_{1}}\left(\alpha_{0}\right)$ and $0 \leq\|\sigma\| \leq \bar{\sigma}$. By virtue of [6, Theorem 2.3, p. 192], the Markov process $\Phi_{\alpha, \sigma}^{\phi}(t)=\left(x_{\alpha, \sigma}(t), y_{\alpha, \sigma}(t)\right)$ has a unique stationary distribution $\mu_{\alpha, \sigma}$ with support $\mathbb{R}^{2,0}$. Further, by $[1,12]$, the stationary distribution $\mu_{\alpha, \sigma}$ has the density with respect to Lebesgue measure on $\mathbb{R}^{2, \circ}$ by the non degenerate property of $g(\phi)$.

On the other hand, it follows from (2.3) that for any $\varepsilon>0$ there exist $R=R(\varepsilon)$ such that $\mu_{\alpha, \sigma}\left(\mathbf{B}_{R}\right) \geq 1-\varepsilon$ for every $\alpha \in \mathcal{U}_{\delta_{1}}\left(\alpha_{0}\right)$ and $0 \leq\|\sigma\| \leq \bar{\sigma}$.

By assumption of Theorem 2.6, it is seen from the item (2) of Lemma 1.1 that $\phi_{\alpha_{0}}^{*}$ is a source point, i.e., two eigenvalues of the matrix $\operatorname{Df}\left(\phi_{\alpha_{0}}^{*}, \alpha_{0}\right)$ have the positive real parts. Therefore, the Lyapunov equation

$$
D f\left(\phi_{\alpha_{0}}^{*}, \alpha_{0}\right)^{\top} P+P D f\left(\phi_{\alpha_{0}}^{*}, \alpha_{0}\right)=I
$$

has a positively definite solution $P$. Since $D f(\phi, \alpha)$ is continuous in $\phi, \alpha$, there exist a positive constants $0<\delta_{2}<\delta_{1}, 0<\delta_{3}$ and $c$ such that

$$
\begin{gather*}
\dot{V}(\phi, \alpha)=V_{\phi}(\phi, \alpha) f(\phi, \alpha)>c\left\|\phi-\phi_{\alpha}^{*}\right\|  \tag{2.35}\\
\operatorname{trace}\left(\mathrm{g}^{\top}(\phi) \operatorname{Pg}(\phi)\right) \geq c\|\sigma\|^{2} \tag{2.36}
\end{gather*}
$$

for all $\phi \in \mathcal{V}_{\delta_{3}}\left(\phi_{\alpha_{0}}^{*}\right), \alpha \in \mathcal{U}_{\delta_{2}}\left(\alpha_{0}\right)$. Where $V(\phi, \alpha)=\left(\phi-\phi_{\alpha}^{*}\right)^{\top} P\left(\phi-\phi_{\alpha}^{*}\right)$. Hence,

$$
\begin{equation*}
\mathcal{L} V(\phi, \alpha)=V_{\phi}(\phi, \alpha) f(\phi, \alpha)+\operatorname{trace}\left(\mathrm{g}^{\top}(\phi) \operatorname{Pg}(\phi)\right) \geq \mathrm{c}\|\sigma\|^{2} \tag{2.37}
\end{equation*}
$$

for all $\phi \in \mathcal{V}_{\delta_{3}}\left(\phi_{\alpha_{0}}^{*}\right), \alpha \in \mathcal{U}_{\delta_{2}}\left(\alpha_{0}\right)$.

Denoting $S=\mathcal{V}_{\delta_{3} / 2}\left(\phi_{\alpha_{0}}^{*}\right)$ and $\mathcal{Z}=\mathcal{V}_{\delta_{3}}\left(\phi_{\alpha_{0}}^{*}\right)$ we now prove that

$$
\begin{equation*}
\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(S)=0 . \tag{2.38}
\end{equation*}
$$

First, we note from (2.35) that there is $T^{*}$ such that if $\phi \in \mathbf{B}_{R} \backslash S$ then $\Phi_{\alpha}^{\phi}(t) \in \mathbf{B}_{R} \backslash \mathcal{Z}$ for all $t \geq T^{*}$. Further, for any $T>0$ we have

$$
\begin{aligned}
& \mu_{\alpha, \sigma}(S)=\int_{\mathbb{R}_{+}^{2}} P_{\alpha, \sigma}(T, \phi, S) \mu_{\alpha, \sigma}(d \phi) \\
& \quad=\int_{\mathbf{B}_{R} \backslash S} P_{\alpha, \sigma}(T, \phi, S) \mu_{\alpha, \sigma}(d \phi)+\int_{S} P_{\alpha, \sigma}(T, \phi, S) \mu_{\alpha, \sigma}(d \phi)+\int_{\mathbf{B}_{R}^{c}} P_{\alpha, \sigma}(T, \phi, S) \mu_{\alpha, \sigma}(d \phi),
\end{aligned}
$$

where $P_{\alpha, \sigma}(T, \phi, \cdot)=\mathbb{P}\left(\Phi_{\alpha, \sigma}^{\phi}(T) \in \cdot\right)$ is the transition probability of the Markov process $\Phi_{\alpha, \sigma}^{\phi}$. It is clear that

$$
\begin{equation*}
\int_{\mathbf{B}_{R}^{c}} P_{\alpha, \sigma}(T, \phi, S) \mu_{\alpha, \sigma}(d \phi) \leq \mu_{\alpha, \sigma}\left(\mathbf{B}_{R}^{c}\right) \leq \varepsilon \tag{2.39}
\end{equation*}
$$

For $\phi \in S$, let $\tau_{\alpha, \sigma}^{\phi}$ be the exit time of $\Phi_{\alpha, \sigma}^{\phi}(\cdot)$ from $\mathcal{Z}$, i.e.,

$$
\begin{equation*}
\tau_{\alpha, \sigma}^{\phi}=\inf \left\{t \geq 0: \Phi_{\alpha, \sigma}^{\phi}(t) \notin \mathcal{Z}\right\} . \tag{2.40}
\end{equation*}
$$

By Itô's formula, we have

$$
\begin{align*}
\theta & \geq \mathbb{E} V\left(\Phi_{\alpha, \sigma}^{\phi}\left(\tau_{\alpha, \sigma}^{\phi} \wedge t\right)\right)-V(\phi)=\mathbb{E} \int_{0}^{\tau_{\alpha, \sigma}^{\phi} \wedge t} \mathcal{L} V\left(\Phi_{\alpha, \sigma}^{\phi}(s)\right) d s  \tag{2.41}\\
& \geq c\|\sigma\|^{2} \mathbb{E}\left[\tau_{\alpha, \sigma}^{\phi} \wedge t\right] \geq c\|\sigma\|^{2} t \mathbb{P}\left(\tau_{\alpha, \sigma}^{\phi} \geq t\right), \quad t \geq 0, \tag{2.42}
\end{align*}
$$

where $\theta=\sup \left\{V(\phi, \alpha): \phi \in \mathcal{Z}, \alpha \in \mathcal{U}_{\delta_{2}}\left(\alpha_{0}\right)\right\}$. Choosing $T_{\sigma}=\max \left\{\frac{2 \theta}{c\|\sigma\|^{2}}, T^{*}\right\}$ obtains

$$
\begin{equation*}
\mathbb{P}\left(\tau_{\alpha, \sigma}^{\phi} \geq T_{\sigma}\right) \leq \frac{1}{2} \tag{2.43}
\end{equation*}
$$

for all $\phi \in S, \alpha \in \mathcal{U}_{\delta_{2}}\left(\alpha_{0}\right)$. Thus,

$$
\begin{align*}
P_{\alpha, \sigma}\left(T_{\sigma}, \phi, S\right) & =\mathbb{P}\left(\Phi^{\phi}\left(T_{\sigma}\right) \in S\right) \\
& =\mathbb{P}\left(\Phi^{\phi}\left(T_{\sigma}\right) \in S, \tau_{\alpha, \sigma}^{\phi} \geq T_{\sigma}\right)+\mathbb{P}\left(\Phi^{\phi}\left(T_{\sigma}\right) \in S, \tau_{\alpha, \sigma}^{\phi}<T_{\sigma}\right)  \tag{2.44}\\
& \leq \frac{1}{2}+\mathbb{P}\left(\Phi^{\phi}\left(T_{\sigma}\right) \in S, \tau_{\alpha, \sigma}^{\phi}<T_{\sigma}\right) \tag{e2. 42}
\end{align*}
$$

By using strong Markov property of the solution, one gets

$$
\begin{aligned}
\mathbb{P}\left(\Phi^{\phi}\left(T_{\sigma}\right)\right. & \left.\in S, \tau_{\alpha, \sigma}^{\phi}<T_{\sigma}\right) \\
& =\int_{0}^{T_{\sigma}}\left[\int_{\partial \mathcal{Z}} \mathbb{P}\left\{\Phi_{\alpha, \sigma}^{\psi}\left(T_{\sigma}-t\right) \in S\right\} \mathbb{P}\left\{\Phi_{\alpha, \sigma}^{\phi}(t) \in d \psi\right\}\right] P\left\{\tau_{\alpha, \sigma}^{\phi} \in d t\right\} .
\end{aligned}
$$

It remarks that when $\psi \in \partial \mathcal{Z}$ we have $\Phi_{\alpha}^{\psi}\left(T_{\sigma}-t\right) \notin \mathcal{Z}$ for all $t \geq 0$. Therefore, by Lemma 2.5 with $\varsigma=\delta_{3} / 2$ we can find $\bar{\sigma}>\kappa>0$ and $0<\delta_{4} \leq \delta_{2}$ such that $\mathbb{P}\left(\Phi_{\alpha, \sigma}^{\psi}\left(T_{\sigma}-t\right) \in S\right) \leq$ $\exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}$ for $0 \leq t \leq T_{\sigma}, 0<\|\sigma\|<\kappa$ and $\alpha \in \mathcal{U}_{\delta_{4}}\left(\alpha_{0}\right)$. Hence,

$$
\begin{equation*}
\mathbb{P}\left\{\Phi^{\phi}\left(T_{\sigma}\right) \in S, \tau_{\alpha, \sigma}^{\phi}<T_{\sigma}\right\} \leq T_{\sigma} \exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}, \alpha \in \mathcal{U}_{\delta_{4}}\left(\alpha_{0}\right), 0<\|\sigma\|<\kappa . \tag{2.45}
\end{equation*}
$$

Combining (2.44) and (2.45) obtains

$$
\int_{S} P\left(T_{\sigma}, \phi, S\right) \mu_{\alpha, \sigma}(d \phi) \leq \frac{1}{2} \mu_{\alpha, \sigma}(S)+T_{\sigma} \exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}, \alpha \in \mathcal{U}_{\delta_{4}}\left(\alpha_{0}\right), 0<\|\sigma\|<\kappa
$$

On the other hand, when $\phi \in \mathbf{B}_{R} \backslash S$ we see that $\Phi_{\alpha}^{\phi}\left(T_{\sigma}\right) \notin \mathcal{Z}$. Therefore, using (2.35) again we get

$$
\int_{\mathbf{B}_{R} \backslash S} P\left(T_{\sigma}, \phi, S\right) \mu_{\alpha, \sigma}(d \phi)<\exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}, \alpha \in \mathcal{U}_{\delta_{4}}\left(\alpha_{0}\right), 0<\|\sigma\|<\kappa .
$$

Summing up we have

$$
\mu_{\alpha, \sigma}(S) \leq \frac{1}{2} \mu_{\alpha, \sigma}(S)+\left(T_{\sigma}+1\right) \exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}+\varepsilon, \alpha \in \mathcal{U}_{\delta_{4}}\left(\alpha_{0}\right), 0<\|\sigma\|<\kappa
$$

Noting that $\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)}\left(T_{\sigma}+1\right) \exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}=0$ we can pass the limit to get

$$
\limsup _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(S) \leq \frac{1}{2} \limsup _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(S)+\varepsilon
$$

Since $\varepsilon>0$ is arbitrary,

$$
\limsup _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(S)=0 .
$$

We now prove (2.34). Let $\mathcal{V}$ be an open set containing $\Gamma_{\alpha_{0}}$. It suffices to show that for any compact set $B$ not intersecting $\mathcal{V}$ nor $S$ we have

$$
\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(B)=0
$$

Let $3 d=\operatorname{dist}\left(\partial \mathcal{V}, \Gamma_{\alpha_{0}}\right)$ and

$$
\mathcal{V}_{d}\left(\Gamma_{\alpha_{0}}\right)=\left\{x: \operatorname{dist}\left(x, \Gamma_{\alpha_{0}}\right)<d\right\} .
$$

From item (ii) of Lemma 1.2, there exists $0<\delta_{5}<\delta_{4}$ such that $\Gamma_{\alpha} \subset \mathcal{V}_{d}\left(\Gamma_{\alpha_{0}}\right)$ for all $\alpha \in \overline{\mathcal{U}}_{\delta_{5}}\left(\alpha_{0}\right)$. It is clear that

$$
\operatorname{dist}\left(B, \mathcal{V}_{d}\left(\Gamma_{\alpha_{0}}\right)\right)>2 d
$$

Let $\varepsilon>0$ and $R=R(\varepsilon)>0$ such that $S, B \subset \mathbf{B}_{R}$ and $\mu_{\alpha, \sigma}\left(\mathbf{B}_{R}^{c}\right) \leq \varepsilon$. Since $\Gamma_{\alpha_{0}}$ is asymptotically stable, we can find an open neighbourhood $U$ of $\Gamma_{\alpha_{0}}$ such that $U \subset \mathcal{V}_{d}\left(\Gamma_{\alpha_{0}}\right)$ and if $\phi \in U$ then $\Phi_{\alpha_{0}}^{\phi}(t) \in \mathcal{V}_{d}\left(\Gamma_{\alpha_{0}}\right)$ for all $t \geq 0$. Further, the simple property of the limit cycle $\Gamma_{\alpha_{0}}$ implies that

$$
\lim _{t \rightarrow \infty} \operatorname{dist}\left(\Phi_{\alpha_{0}}^{\phi}(t), \Gamma_{\alpha_{0}}\right)=0 \text { for all } \phi \notin S .
$$

This means that for every $\phi \in \overline{\mathbf{B}}_{R} \backslash S$, there exists a $T^{\phi}$ such that $\Phi_{\alpha_{0}}^{\phi}(t) \in U$ for all $t \geq T^{\phi}$.
By the continuity of solutions on the initial condition, there exist $\delta_{\phi}>0$ such that $\Phi_{\alpha_{0}}^{z}(t) \in U$ for all $z \in \mathcal{V}_{\delta_{\phi}}(\phi)$ and $t>T^{\phi}$. Since $\overline{\mathbf{B}}_{R} \backslash S$ is compact, there is $\phi_{1}, \phi_{2}, \ldots, \phi_{n}$ such that $\overline{\mathbf{B}}_{R} \backslash S \subset \cup_{k=1}^{n} \mathcal{V}_{\delta_{\phi_{k}}}\left(\phi_{k}\right)$. Let $T=\max \left\{T^{\phi_{1}}, T^{\phi_{2}}, \ldots, T^{\phi_{n}}\right\}$. It is seen that

$$
\Phi_{\alpha_{0}}^{\phi}(T) \in U \subset \mathcal{V}_{d}\left(\Gamma_{\alpha_{0}}\right) \text { for all } \phi \in \overline{\mathbf{B}}_{R} \backslash S
$$

Similar as above, we have

$$
\begin{align*}
\mu_{\alpha, \sigma}(B) & =\int_{\mathbf{B}_{R} \backslash S} P_{\alpha, \sigma}(T, \phi, B) \mu_{\alpha, \sigma}(d \phi)+\int_{S} P_{\alpha, \sigma}(T, \phi, B) \mu_{\alpha, \sigma}(d \phi)+\int_{\mathbf{B}_{R}^{c}} P_{\alpha, \sigma}(T, \phi, B) \mu_{\alpha, \sigma}(d \phi) \\
& \leq \int_{\mathbf{B}_{R} \backslash S} P_{\alpha, \sigma}(T, \phi, B) \mu_{\alpha, \sigma}(d \phi)+\mu_{\alpha, \sigma}(S)+\mu_{\alpha, \sigma}\left(\mathbf{B}_{R}^{c}\right) \\
& \leq \int_{\mathbf{B}_{R} \backslash S} P_{\alpha, \sigma}(T, \phi, B) \mu_{\alpha, \sigma}(d \phi)+\mu_{\alpha, \sigma}(S)+\varepsilon . \tag{2.46}
\end{align*}
$$

Using the Lemma 2.5 again with $\varsigma=d$ we can find $\delta_{6}<\delta_{5}$ and $\kappa_{1}$ such that

$$
\mathbb{P}\left\{\left\|\Phi_{\alpha, \sigma}^{\phi}(T)-\Phi_{\alpha}^{\phi}(T)\right\| \geq \varsigma\right\} \leq \exp \left\{-\frac{\kappa_{1}}{\|\sigma\|^{2}}\right\}, \alpha \in \mathcal{U}_{\delta_{6}}\left(\alpha_{0}\right), \phi \in \mathbf{B}_{R} \backslash S, 0<\|\sigma\|<\kappa_{1}
$$

This inequality implies that

$$
\mathbb{P}\left\{\| \Phi_{\alpha, \sigma}^{\phi}(T) \in \mathcal{V}\right\} \geq 1-\exp \left\{-\frac{\kappa_{1}}{\|\sigma\|^{2}}\right\}, \alpha \in \mathcal{U}_{\delta_{6}}\left(\alpha_{0}\right), \phi \in \mathbf{B}_{R} \backslash S, 0<\|\sigma\|<\kappa_{1} .
$$

Since $B \cap \mathcal{V}=\emptyset$,

$$
P_{\alpha, \sigma}(T, \phi, B)=\mathbb{P}\left\{\| \Phi_{\alpha, \sigma}^{\phi}(T) \in B\right\} \leq \exp \left\{-\frac{\kappa_{1}}{\|\sigma\|^{2}}\right\}, \alpha \in \mathcal{U}_{\delta_{6}}\left(\alpha_{0}\right), \phi \in \mathbf{B}_{R} \backslash S, 0<\|\sigma\|<\kappa_{1}
$$

Hence,

$$
\mu_{\alpha, \sigma}(B) \leq \exp \left\{-\frac{\kappa_{1}}{\|\sigma\|^{2}}\right\}+\mu_{\alpha, \sigma}(S)+\varepsilon
$$

Thus,

$$
\limsup _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(B) \leq \lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)}\left(\exp \left\{-\frac{\kappa}{\|\sigma\|^{2}}\right\}+\mu_{\alpha, \sigma}(S)+\varepsilon\right)=\varepsilon
$$

Since $\varepsilon$ is arbitrary,

$$
\limsup _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(B)=0
$$

The proof is complete.
Corollary 2.7. Suppose that all of assumptions of the theorem 2.6 hold. If $H$ is continuous and bounded function defined on $\mathbb{R}_{+}^{2}$, then

$$
\begin{equation*}
\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \int_{\mathbb{R}_{+}^{2}} H(x) d \mu_{\alpha, \sigma}(x)=\frac{1}{T^{*}} \int_{0}^{T^{*}} H\left(\Phi_{\alpha_{0}}^{\bar{\phi}}(t)\right) d t \tag{2.47}
\end{equation*}
$$

where $\bar{\phi}$ is any point on $\Gamma_{\alpha_{0}}$ and $T^{*}$ is the period of the limit cycle, i.e., $\Phi_{\alpha_{0}}^{\bar{\phi}}\left(t+T^{*}\right)=\Phi_{\alpha_{0}}^{\bar{\phi}}(t)$. Proof. Let $\widehat{\Phi}_{\alpha, \sigma}(\cdot)$ be the stationary solution of (1.5), whose distribution is $\mu_{\alpha, \sigma}$. We see that

$$
\int_{\mathbb{R}_{+}^{2}} H(\phi) d \mu_{\alpha, \sigma}(\phi)=\mathbb{E} H\left(\widehat{\Phi}_{\alpha, \sigma}(t)\right), \text { for all } t \geq 0
$$

In particular,

$$
\int_{\mathbb{R}_{+}^{2}} H(\phi) d \mu_{\alpha, \sigma}(\phi)=\frac{1}{T^{*}} \int_{0}^{T^{*}} H\left(\widehat{\Phi}_{\alpha, \sigma}(t)\right) d t
$$

where $T^{*}$ is the period of the cycle. Since the measure $\mu_{\alpha, \sigma}(\cdot)$ becomes concentrated on the cycle $\Gamma_{\alpha_{0}}$ as $(\alpha, \sigma)$ approaches to $\left(\alpha_{0}, 0\right)$ and $H$ is bounded continuous function, we obtain

$$
\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \int_{\mathbb{R}_{+}^{2}} H(\phi) d \mu_{\alpha, \sigma}(\phi)=\frac{1}{T^{*}} \int_{0}^{T^{*}} H\left(\Phi_{\alpha_{0}}^{\bar{\phi}}(t)\right) d t
$$

where $\bar{\phi}$ is any point on the limit cycle $\Gamma_{\alpha_{0}}$. The proof is completed.
thm2.2 Theorem 2.8. Let $\alpha_{0}=\left(r_{0}, m_{0}, \beta_{0}, \gamma_{0}, a_{0}, b_{0}, c_{0}\right)$ be a vector of parameters of the system (1.1) such that $\lambda_{\alpha_{0}}>0$ and $b_{0} \geq \min \left\{\frac{c_{0}}{\beta_{0}}, \frac{m_{0}^{2} \beta_{0}^{2}-c_{0}^{2} \gamma_{0}^{2}}{\gamma_{0} \beta_{0}\left(m_{0} \beta_{0}-c_{0} \gamma_{0}\right)+m_{0} r_{0} \beta_{0}^{2}}\right\}$.

Then, there exist $\delta>0$ and $\bar{\sigma}>0$ such that for all $\alpha \in \mathcal{U}_{\delta}\left(\alpha_{0}\right)$ and $0<\sigma \leq \bar{\sigma}$, the process $\left(x_{\alpha, \sigma}(t), y_{\alpha, \sigma}(t)\right)$ has a stationary distribution $\mu_{\alpha, \sigma}$ concentrated on $\mathbb{R}_{+}^{2, \circ}$. Further for any open set $\mathcal{V}$ containing the positive equilibrium point $\phi_{\alpha_{0}}^{*}=\left(x_{\alpha_{0}}^{*}, y_{\alpha_{0}}^{*}\right)$ of the system (1.1)

$$
\begin{equation*}
\lim _{(\alpha, \sigma) \rightarrow\left(\alpha_{0}, 0\right)} \mu_{\alpha, \sigma}(\mathcal{V})=1 \tag{2.48}
\end{equation*}
$$

Proof. The proof is quite similar as the one of Theorem 2.4. So, we omit it here.

## 3 Numerical Examples

ex1 Example 3.1. Consider (1.1) having the parameter $\alpha_{0}$ with $r_{0}=1, K_{0}=5, m_{0}=9, a_{0}=$ $1.75, b_{0}=1, c_{0}=1, \gamma_{0}=0.6, \beta_{0}=0.5$. Direct calculation shows that $\lambda_{\alpha}=2.7582>$ 0 and a positive equilibrium $\left(x^{*}, y^{*}\right)=(0.3,0.233)$ with $D f\left(x^{*}, y^{*}\right)$ has two eigenvalues $0.0016 \pm 0.66 i$. Further, $b_{0} \leq \min \left\{\frac{c_{0}}{\beta_{0}}, \frac{m_{0}^{2} \beta_{0}^{2}-c_{0}^{2} \gamma_{0}^{2}}{\gamma_{0} \beta_{0}\left(m_{0} \beta_{0}-c_{0} \gamma_{0}\right)+m_{0} r_{0} \beta_{0}^{2}}\right\}$. Thus, this system has a limit cycle $\Gamma_{0}$ simulated in Figure 1, starting from the point $(0.67,0.2)$. Let $\mathcal{V}$ be an $\varepsilon-$ neighbourhood of $\Gamma_{0}$ with $\varepsilon=0.01$. For $\|\sigma\| \leq 1$, we have $\lambda_{\alpha, \sigma}>0$. This means that (1.5) has a unique stationary distribution $\mu_{\alpha, \sigma}$. We estimate the probability $\mu_{\alpha, \sigma}(\mathcal{V})$ as $\sigma \rightarrow 0$. To simplify the simulation, we fix all other parameters, excepted the variation of $a$ and list results in the following table.

| $\sigma$ | $(0.5,0.5)$ | $(0.1,0.1)$ | $(0.01,0.01)$ | $(0.001,0.001)$ |
| :---: | :---: | :---: | :---: | :---: |
| $a$ | 1.8 | 1.75 | 1.72 | 1.71 |
| $\lambda_{\alpha, \sigma}$ | 2.3975 | 2.72 | 2.7450 | 2.7500 |
| $\mu_{\alpha, \sigma}(\mathcal{V})$ | 0.1575 | 0.3380 | 0.7001 | 0.8960 |



Figure 1: A: Limit cycle $\Gamma_{0}$ of (1.1); B: Sample path of (1.5) when $a=1.78, \sigma=0.5$; C: Sample path of (1.5) when $a=1.75, \sigma=0.1$.


Figure 2: D: Sample path of (1.5) when $a=1.2, \sigma=0.01$; E: Sample path of (1.5) when $a=1.71, \sigma=0.001$.

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