Machine learning 5. SVM

V. Lefieux

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Table of contents

Separable case

Non separable case

Non linear SVM: kernel trick

Separable case

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Non linear SVM: kernel trick

References

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Table of contents

Separable case

Non separable case

Non linear SVM: kernel trick

Separable case

Non separable case

Non linear SVM: kernel trick

References

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 Support Vector Machine (large machine classifiers) are supervised learning algorithms.

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- Available for classification and regression.
- These algorithms are required to have good generalization properties: compromise between estimation and prediction.

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References

Presentation

- In the case of a binary classification 𝒴 = {−1, 1} with 𝒴 = ℝ^d.
- The SVM (Vapnik) approach can be seen as a generalization of "optimal hyperplane search".

Simple case

Data $(x_1, y_1), \ldots, (x_n, y_n)$ are linearly separable if there exists $(w, b) \in \mathbb{R}^d \times \mathbb{R}$ such that for all *i*:

•
$$y_i = 1$$
 if $\langle w, x_i \rangle + b > 0$,
• $y_i = -1$ if $\langle w, x_i \rangle + b < 0$.

i.e.:

$$\forall i \in \{1,\ldots,n\} : y_i(\langle w, x_i \rangle + b) > 0$$
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References



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Problem

There is an infinite of infinite of separating hyperplanes so an infinite of potential classification rules.

Solution

Vapnik proposes to choose the hyperplane with the largest margin.



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Margin



$$b \quad d(x) = \frac{\|\langle w, x \rangle + b\|}{\|w\|} = \\ x^\top w + b \text{ if } \|w\| = 1$$

 if (w, b) is the optimal separating hyperplan, its margin is:

$$\min_{i\in\{1,\ldots,n\}} y_i\left(w_i^\top x_i + b\right) \ .$$

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Optimal separating hyperplan Solution of the constrained optimization problem:

$$\max_{\substack{w,b, \|w\|=1}} M$$

under constraint $\forall i \in \{1, \dots, n\} : y_i \left(w^\top x_i + b\right) \ge M$.

Rewriting

► If we remove the constraint ||w|| = 1, then we seek the largest margin such that:

$$\forall i \in \{1,\ldots,n\} : y_i \left(w^\top x_i + b\right) \geq \|w\| M.$$

• With the new constraint $||w|| = \frac{1}{M}$, optimization problem becomes:

Primal problem

$$\min_{w,b}\frac{1}{2}\|w\|^2$$

under constraint $\forall i \in \{1, \ldots, n\} : y_i (w^\top x_i + b) \ge 1$.

- Problem of convex optimization under linear constraints.
- Existence of a optimum global obtained by resolution of the dual problem.

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Resolution by lagrangian method I

The lagrangien of the primal problem is:

$$L_{p}(w, b; \alpha) = \frac{1}{2} \|w\|^{2} - \sum_{i=1}^{n} \alpha_{i} \left[y_{i}(x_{i}^{\top}w + b) - 1 \right]$$

Considering partial derivatives with respect of w and b:

$$w = \sum_{i=1}^{n} \alpha_i y_i x_i$$
 et $\sum_{i=1}^{n} \alpha_i y_i = 0$.

Dual problem

By substituting these two equations in L_p , we obtain the dual problem which consists in maximizing:

$$L_D(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \alpha_i \alpha_k y_i y_k x_i^\top x_k$$

under contraints $\alpha_i \geq 0$ and $\sum_{i=1}^{n} \alpha_i y_i = 0$.

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Resolution by lagrangian method II

- We note α^* the dual problem solution.
- We then deduce:

$$w^{\star} = \sum_{i=1}^{n} \alpha_i^{\star} y_i x_i \; .$$

Karush-Kuhn-Tucker conditions (KKT)

►
$$\forall i \in \{1, \dots, n\} : \alpha_i^* \ge 0$$
,
► $\forall i \in \{1, \dots, n\} : \alpha_i^* [y_i (x_i^\top w + b) - 1] = 0$

We obtain b^{*} by solving:

$$\alpha_i^{\star}\left[y_i\left(x_i^{\top}w+b\right)-1\right]=0$$

for α_i^* non-zero.

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Support vectors

► x_i such that α^{*}_i > 0 check:

$$y_i\left(x_i^{\top}w^{\star}+b^{\star}\right)=1$$
.

 So they are on the border with the maximal margin. These points are called support vectors.

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Separable case

Von separable case

Non linear SVM: kernel trick

Table of contents

Separable case

Non separable case

Non linear SVM: kernel trick

Separable

Non separable case

Non linear SVM: kernel trick

References

Problem

In the majority of cases, data aren't linearly separable...



Separable case

Non separable case

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References

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Non separable case

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References

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Reminder: separable case

$$\begin{split} \min_{w,b} \frac{1}{2} \|w\|^2 \\ \text{under constraint} \quad \forall i \in \{1, \dots, n\} : y_i \left(w^\top x_i + b\right) \geq 1 \;. \end{split}$$

► The contraints y_i (w^Tx_i + b) ≥ 1 mean that all points are outside the boundary defined by the margin.

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Non separable case

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Reminder: separable case

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- The contraints y_i (w[⊤]x_i + b) ≥ 1 mean that all points are outside the boundary defined by the margin.
- Non separable case: the problem below does not admit a solution !

Slack variables creation !

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To allow certain points to be "in the margin" and/or misclassified, we define positive slack variables (ξ_1, \ldots, ξ_n) such as $y_i (w^\top x_i + b) \ge 1 - \xi_i$. 2 cases are to be distinguished:

1. $\xi_i \in [0, 1] \Rightarrow$ well classified but in the region defined by the margin.

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2. $\xi_i > 1 \Rightarrow$ misclassified.

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Non linear SVM: kernel trick

- Of course, we would like to have the maximum of slack variables ξ_i zero.
- When $\xi_i > 0$, one expect ξ_i to be the smallest possible.

Non separable case: primal optimization problem

• We want to find the
$$(w, b, \xi)$$
 value that minimize:

$$\frac{1}{2} \|w\|^2$$

under the constraints:

$$\begin{cases} y_i (w^\top x_i + b) \ge 1 \quad , i = 1, \dots, n. \end{cases}$$

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- When $\xi_i > 0$, one expect ξ_i to be the smallest possible.

Non separable case: primal optimization problem

• We want to find the
$$(w, b, \xi)$$
 value that minimize:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i$$

under the constraints:

$$\begin{cases} y_i (w^{\top} x_i + b) \ge 1 - \xi_i, \ i = 1, \dots, n. \\ \xi_i \ge 0, i = 1, \dots, n. \end{cases}$$

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Non separable case

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References

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Non separable case: primal optimization problem

• We want to find the
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 value that minimize:

$$\frac{1}{2} \|w\|^2 + C \sum_{i=1}^n \xi_i$$

under the constraints:

$$\begin{cases} y_i \left(w^\top x_i + b \right) \ge 1 - \xi_i, \ i = 1, \dots, n. \\ \xi_i \ge 0, i = 1, \dots, n. \end{cases}$$

- ► The separable case corresponds to $C = +\infty$.

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Optimization solution

The solutions of this new optimization problem are obtained in the same way: lagrangian, dual problem...

KKT conditions

1. $0 \le \alpha_i^* \le C$. 2. $y_i(\langle w^*, x_i \rangle + b^*) \ge 1 - \xi_i^*$. 3. $\alpha_i^*(y_i(\langle w^*, x_i \rangle + b^*) + \xi_i^* - 1) = 0$. 4. $\xi_i^*(\alpha_i^* - C) = 0$.

Support vectors

- x_i such as $\alpha_i^* > 0$ are support vectors.
- There are two types:
 - 1. those on the border defined by the margin: $\xi_i^{\star} = 0$;
 - 2. those outside: $\xi_i^* > 0$ and $\alpha_i^* = C$.
- Non support vectors check $\alpha_i^{\star} = 0$ et $\xi_i^{\star} = 0$.

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Classification rule

As in the separable case, the optimal hyperplane is defined by:

$$w^{\star} = \sum_{i=1}^{n} \alpha_i^{\star} y_i x_i$$

and b^* is the solution of $y_i (\langle w^*, x_i \rangle + b^*) = 1$ for any i such as $0 < \alpha_i^* < C$.

We deduce the SVM classification rule:

$$g(x) = \mathbb{1}_{\langle w^{\star}, x \rangle + b^{\star} \geq 0} - \mathbb{1}_{\langle w^{\star}, x \rangle + b^{\star} < 0}$$
.

• The maximum margin is $\frac{1}{\|w^{\star}\|} = \left[\sum_{i=1}^{n} (\alpha_i^{\star})^2\right]^{-1/2}$.

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Choice of C

- It's crucial to the performance of the SVM.
- Il est le plus souvent choisi de faon "classique":
 - 1. We consider a performance criterion (e. g. misclassification rate).
 - 2. We estimate the value of the criterion for different values of *C*.
 - 3. We choose the value of C whoc minimizes the criterion.

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Non separable case

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References

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Table of contents

Separable case

Non separable case

Non linear SVM: kernel trick

Separable ca

Von separable case

Non linear SVM: kernel trick

References

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Separable case

Von separable case

Non linear SVM: kernel trick

References

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Separable case

Von separable case

Non linear SVM: kernel trick

References

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Separable case

Non separable case

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Find a data transformation such that the transformed data are linearly separable.

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Kernel

Let $\Phi:\mathcal{X}\to\mathcal{H}$ be an application from \mathcal{X} to a Hilbert space $\mathcal{H}.$

The kernel *K* at values *x* and *x'*, associated to Φ , is the inner product of $\Phi(x)$ and $\Phi(x')$:

$$\begin{split} \mathcal{K} &: \mathcal{X} \times \mathcal{X} \to \mathbb{R} \\ & \left(x, x' \right) \mapsto \langle \Phi(x), \Phi\left(x' \right) \rangle_{\mathcal{H}}. \end{split}$$

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Kernel

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ightarrow \mathbb{R} \ ig(x,x') \mapsto \langle \Phi(x), \Phiig(x')
angle_{\mathcal{H}}. \end{aligned}$$

Example

If
$$\mathcal{X} = \mathcal{H} = \mathbb{R}^2$$
 and $\Phi(x_1, x_2) = \left(x_1^2, x_2^2\right)$ then:

$$K(x, x') = (x_1)^2 (x'_1)^2 + (x_2)^2 (x'_2)^2$$
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► The trick consists in transforming data x_i in a Hilbert space H called feature space...

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Von separable case

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- ► The trick consists in transforming data x_i in a Hilbert space H called feature space...
- ... expecting that (Φ(x₁), y₁),..., (Φ(x_n), y_n) are (almost) linearly separables in order to apply SVM on transformed data.

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- ... expecting that (Φ(x₁), y₁),..., (Φ(x_n), y_n) are (almost) linearly separables in order to apply SVM on transformed data.
- 1. A lot of linear algorithms (in particular SVM) can be applied to $\Phi(x)$ without ever computing Φ . All we have to do is to compute K(x, x').

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- ... expecting that (Φ(x₁), y₁),..., (Φ(x_n), y_n) are (almost) linearly separables in order to apply SVM on transformed data.
- 1. A lot of linear algorithms (in particular SVM) can be applied to $\Phi(x)$ without ever computing Φ . All we have to do is to compute K(x, x').
- 2. We don't need to know the space \mathcal{H} or the function Φ , we just need to consider a kernel K!

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SVM in the inital space

The dual problem maximises:

$$L_D(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \alpha_i \alpha_k y_i y_k \langle \mathbf{x}_i, \mathbf{x}_k \rangle$$

under the constraints:

$$\begin{cases} \forall i \in \{1, \dots, n\} : 0 \le \alpha_i \le C\\ \sum_{i=1}^n \alpha_i y_i = 0. \end{cases}$$

The decision rule is obtained by calculating the sign of:

$$f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_i^* y_i \langle \mathbf{x}_i, \mathbf{x} \rangle + b^* .$$

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SVM in the feature space

The dual problem maximises:

$$L_D(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \alpha_i \alpha_k y_i y_k \langle \Phi(\mathbf{x}_i), \Phi(\mathbf{x}_k) \rangle$$

under the consraints:

$$\begin{cases} \forall i \in \{1, \dots, n\} : 0 \le \alpha_i \le C\\ \sum_{i=1}^n \alpha_i y_i = 0. \end{cases}$$

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The decision rule is obtained by calculating the sign of:

$$f(x) = \sum_{i=1}^{n} \alpha_i^* y_i \langle \Phi(x_i), \Phi(x) \rangle + b^* .$$

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SVM in the feature space with kernels

The dual problem maximises:

$$L_D(\alpha) = \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{k=1}^n \alpha_i \alpha_k y_i y_k \mathbf{K}(\mathbf{x}_i, \mathbf{x}_k)$$

under the consraints:

$$\begin{cases} \forall i \in \{1, \dots, n\} : 0 \le \alpha_i \le C\\ \sum_{i=1}^n \alpha_i y_i = 0. \end{cases}$$

The decision rule is obtained by calculating the sign of:

$$f(\mathbf{x}) = \sum_{i=1}^{n} \alpha_i^* y_i \mathbf{K}(\mathbf{x}_i, \mathbf{x}) + b^* .$$

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Non separable case

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References

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Conclusion

To compute SVM, we don't need to know H or Φ, we just need to know K!

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References

Conclusion

- To compute SVM, we don't need to know H or Φ, we just need to know K!
- Questions: What's a kernel ? How to build a kernel ?

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References

Conclusion

- To compute SVM, we don't need to know H or Φ, we just need to know K!
- Questions: What's a kernel ? How to build a kernel ?

 $K : \mathcal{X} \times \mathcal{X} \to \mathbb{R}$ is a kernel if and only if it's a symetric and positive definite function :

1.
$$\forall (x, x') \in \mathcal{X}^2 : \mathcal{K} (x, x') = \mathcal{K} (x', x)$$
.
2. $\forall (x_1, \dots, x_N) \in \mathcal{X}^N$ et $\forall (a_1, \dots, a_N) \in \mathbb{R}^N$:

$$\sum_{i=1}^{N}\sum_{j=1}^{N}a_{i}a_{j}K\left(x_{i},x_{j}\right)\geq0.$$

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References

Example



then $K(x, x') = (x^{\top}x')^2$.

Kernel examples

1. Linear (on
$$\mathbb{R}^d$$
): $K(x, x') = x^\top x'$.

- 2. Polynomial (on \mathbb{R}^d): $K(x, x') = (x^{\top}x' + 1)^d$.
- 3. Gaussian (Gaussian radial basis function ou RBF) (on \mathbb{R}^d):

$$\mathcal{K}\left(x,x'
ight) = \exp\left(-rac{\|x-x'\|}{2\sigma^2}
ight) \; .$$

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- 4. Laplace (sur \mathbb{R}): $\mathcal{K}(x, x') = \exp(-\gamma |x x'|)$.
- 5. Min (sur \mathbb{R}^+): $K(x, x') = \min(x, x')$.

Separable case

Von separable case

Non linear SVM: kernel trick

Kernel examples

1. Linear (on
$$\mathbb{R}^d$$
): $K(x, x') = x^\top x'$.

- 2. Polynomial (on \mathbb{R}^d): $K(x, x') = (x^{\top}x' + 1)^d$.

$$K(x, x') = \exp\left(-\frac{\|x - x'\|}{2\sigma^2}\right)$$

- 4. Laplace (sur \mathbb{R}): $K(x, x') = \exp(-\gamma |x x'|)$.
- 5. Min (sur \mathbb{R}^+): $K(x, x') = \min(x, x')$.

Any positive definite function works... It's possible to build kernels (and so ti apply SVM) on more complex objects (curves, images, texts...).

Separable case

Von separable case

Non linear SVM: kernel trick

References

Separable case Non separable case

Non linear SVM: kernel trick

References

Vapnik, V. N. (1998). *Statistical learning theory*. Adaptive and learning systems for signal processing, communications, and control. Wiley.

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